

Weighted ℓ_p -Minimization for Sparse Signal Recovery under Arbitrary Support Prior

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Dedicated to Prof. Shanzhen Lu with admiration on the occasion of his 80th birthday

Abstract. Weighted ℓ_p ($0 < p \leq 1$) minimization has been extensively studied as an effective way to reconstruct a sparse signal from compressively sampled measurements when some prior support information of the signal is available. In this paper, we consider the recovery guarantees of k -sparse signals via the weighted ℓ_p ($0 < p \leq 1$) minimization when arbitrarily many support priors are given. Our analysis enables an extension to existing works that assume only a single support prior is used.

Key Words: Adaptive recovery, compressed sensing, weighted ℓ_p minimization, sparse representation, restricted isometry property.

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1 Introduction

Compressed sensing [2, 5] is a new data acquisition paradigm, which reliably recovers a high dimensional sparse signal $x \in \mathbb{R}^n$ (a signal is called k -sparse if the number of its nonzero entries has at most $k \ll n$) from significantly fewer linear observations

$$y = \Phi x + e, \quad (1.1)$$

where $\Phi \in \mathbb{R}^{m \times n}$ is a measurement matrix and $e \in \mathbb{R}^m$ denotes additive noise that satisfies $\|e\|_2 \leq \epsilon$ for some known $\epsilon \geq 0$. Compressed sensing is nonadaptive because the measurement matrix Φ does not depend on the signal being measured. But, some

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prior information of the signal \mathbf{x} may be included in the estimates of the support of \mathbf{x} or some estimates of largest coefficients of \mathbf{x} in some settings. For example, video and audio signals exhibit strong correlation over temporal frames, which can be used to estimate a portion of the support based on previously decoded frames (see [6]). Therefore, the recovery of the signal \mathbf{x} incorporating prior support information has received much attention including the weighted ℓ_1 -minimization [3, 4, 6, 14, 16, 17, 19], the weighted ℓ_p ($0 < p < 1$)-minimization [10, 11, 13, 18] and the greedy algorithm with partial support information [7, 12, 15].

This paper considers the recovery of the signal \mathbf{x} from (1.1) and is devoted to new RIP bounds for the exact and stable recovery of sparse signals with arbitrary many support priors via the weighted ℓ_p -minimization:

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{x}\|_{p, \mathbf{w}}^p \quad \text{subject to} \quad \|\Phi \mathbf{x} - \mathbf{y}\|_2 \leq \varepsilon, \quad (1.2)$$

where $\mathbf{w} \in [0, 1]^n$ is a weight vector and

$$\|\mathbf{x}\|_{p, \mathbf{w}} = \left(\sum_{i=1}^n w_i |x_i|^p \right)^{\frac{1}{p}}.$$

The main idea inherited in the weighted ℓ_p ($0 < p \leq 1$)-minimization is to make the entries of \mathbf{x} , which are “expected” to be large, be penalized less in the weighted objective function in (1.2) by the effect of the weight \mathbf{w} .

As $p = 1$, the method (1.2) reduces to the weighted ℓ_1 -minimization:

$$\min_{\mathbf{x} \in \mathbb{R}^n} \|\mathbf{x}\|_{1, \mathbf{w}} \quad \text{subject to} \quad \|\Phi \mathbf{x} - \mathbf{y}\|_2 \leq \varepsilon. \quad (1.3)$$

The rest of the paper is organized as follows. In Section 2, we recall a recently established RIP bound for signal recovery by virtue of the weighted ℓ_p -minimization with a single weight. In Section 3, we respectively present sufficient conditions for the recovery of sparse signals by weighted ℓ_p -minimization with non-uniform weights in both the noiseless and ℓ_2 bounded noise. Section 4 is devoted to the proofs of the main results.

2 Weighted ℓ_p -minimization with a single weight

Let $\tilde{T} \subseteq [n] = \{1, 2, \dots, n\}$ be a known single support estimate of \mathbf{x} . The weight vector \mathbf{w} in this case is taken by

$$w_i = \begin{cases} \omega, & i \in \tilde{T}, \\ 1, & i \in \tilde{T}^c, \end{cases} \quad (2.1)$$

for some fixed $\omega \in [0, 1]$ and $i \in [n]$.

The restricted isometry property (RIP) is one of the main tools used to evaluate the recovery performance via a variety of efficient algorithms. The RIP notion introduced by Candès et al. in [2], is the most widely used framework in compressed sensing.

Definition 2.1. For a matrix $\Phi \in \mathbb{R}^{m \times n}$ and an integer $1 \leq k \leq n$, Φ is said to satisfy the RIP of order k if there exists a constant $\delta_k \in [0, 1)$ such that

$$(1 - \delta_k)\|x\|_2^2 \leq \|\Phi x\|_2^2 \leq (1 + \delta_k)\|x\|_2^2 \tag{2.2}$$

holds for all k -sparse signals $x \in \mathbb{R}^n$. The smallest constant δ_k is called the restricted isometry constant (RIC) of order k for Φ .

When k is not an integer, δ_k is defined as $\delta_{\lceil k \rceil}$ in [1], where $\lceil k \rceil$ denotes an integer satisfying $k \leq \lceil k \rceil < k + 1$.

The main result of [9] generalizes the recovery condition from [21] to the weighted ℓ_p -minimization (1.2) where the weight vector w is specified in (2.1).

Theorem 2.1 below states the main result of [9] which presents a sufficient condition for the exact recovery of sparse signal x from $y = \Phi x$.

Theorem 2.1. Let x be an arbitrary k -sparse vector in \mathbb{R}^n with $T = \text{supp}(x)$ and $y = \Phi x$. Let $\tilde{T} \subseteq [n]$ be an arbitrary set and $\rho \geq 0$ and $0 \leq \alpha \leq 1$ with $\alpha\rho \leq 1$ such that $|\tilde{T}| = \rho k$ and $|\tilde{T} \cap T| = \alpha\rho k$. Given the weight $\omega \in [0, 1]$ and $0 < p \leq 1$, define some important parameters somehow depending on the weight ω , and the size and the overlap of the true signal support T and the prior support estimate \tilde{T} , and p as follows

- The constant ζ :

$$\zeta = \left(\omega + (1 - \omega)(1 + \rho - 2\alpha\rho)^{\frac{2-p}{2}} \right)^{\frac{2}{2-p}}, \tag{2.3}$$

- the constant d :

$$d = \begin{cases} 1, & \omega = 1, \\ 1 + (\max\{0, 1 - 2\alpha\})\rho, & 0 \leq \omega < 1, \end{cases} \tag{2.4}$$

- the parameter Θ is defined by

$$\Theta = \frac{\zeta}{t - d} \tag{2.5}$$

- for $\Theta > 0$, the quantity $\delta(p, \Theta)$ is defined by

$$\delta(p, \Theta) = \begin{cases} \frac{1}{\sqrt{p^2 + (2 - p)^2\Theta} - (1 - p)}, & \Theta \geq \Theta_0 = \frac{2 + p}{2 - p}, \\ \frac{z_0}{(2 - p)\Theta - z_0}, & \Theta < \Theta_0, \end{cases} \tag{2.6}$$

where $z_0 \in ((1 - p)\Theta, \min(1, \frac{2-p}{2}\Theta))$ is the only positive solution of the equation

$$\frac{p}{2}z^{\frac{2}{p}} + z - \frac{(2 - p)\Theta}{2} = 0. \tag{2.7}$$

Moreover, for $\Theta = \frac{\zeta}{t - d} = 0$, we define $\delta(p, \Theta) = 1$.

If the measurement matrix Φ satisfies RIP with

$$\delta_{tk} < \delta(p, \Theta) \quad (2.8)$$

for $d < t \leq 2d$, then the weighted ℓ_p -minimization (1.2) with the weight vector \mathbf{w} defined in (2.1) and $0 < p \leq 1$ recovers \mathbf{x} exactly.

3 Weighted ℓ_p -minimization with non-uniform weights

In this section, we present our main results for generalizing the weighted ℓ_p -minimization theory of [9], to allow for arbitrary weight assignments.

We consider the weighted ℓ_p -minimization with L distinct weights, where $1 \leq L \leq n$. Let $\tilde{T}_j \subseteq [n]$ be arbitrary L disjoint sets and denote $\rho_j \geq 0$ and $0 \leq \alpha_j \leq 1$ such that $|\tilde{T}_j| = \rho_j k$ and $|\tilde{T}_j \cap T| = \alpha_j \rho_j k$, $j = 1, \dots, L$, where $\rho_j \geq 0$ and $0 \leq \alpha_j \leq 1$ are called the relative size and accuracy for each $j = 1, \dots, L$. Define $\tilde{T} = \cup_{j=1}^L \tilde{T}_j$. The weight vector \mathbf{w} in this general case is chosen in the following way

$$\mathbf{w}_i = \begin{cases} \omega_j, & i \in \tilde{T}_j, \\ 1, & i \in \tilde{T}^c, \end{cases} \quad (3.1)$$

for $i \in [n]$ and $\omega_j \in [0, 1]$, $j = 1, \dots, L$ are given weights.

We first provide a recovery guarantee for the weighted ℓ_p -minimization with L distinct weights in noiseless case.

Theorem 3.1. For $0 < p \leq 1$ and $\mathbf{y} = \Phi \mathbf{x}$, suppose that \mathbf{x} be k -sparse with $T = \text{supp}(\mathbf{x})$. Let $\tilde{T}_i \subseteq [n]$ be arbitrary L disjoint sets and $\rho_i \geq 0$ and $0 \leq \alpha_i \leq 1$ such that $|\tilde{T}_i| = \rho_i k$ and $|\tilde{T}_i \cap T| = \alpha_i \rho_i k$, $i = 1, \dots, L$. Without loss of generality, assume that the weights in (3.1) are ordered so that $0 \leq \omega_L \leq \dots \leq \omega_1 \leq 1$. Let

$$\beta_i = \max \left\{ \sum_{j=i}^L \alpha_j \rho_j, \sum_{j=i}^L (1 - \alpha_j) \rho_j \right\},$$

$$b_i = \begin{cases} 1, & i = 1, \\ \text{sgn}(\omega_{i-1} - \omega_i), & i = 2, \dots, L, \end{cases}$$

and

$$d = \begin{cases} 1, & \omega_1 = \omega_2 = \dots = \omega_L = 1, \\ \max_{i \in \{1, 2, \dots, L\}} \left\{ b_i \left(1 - \sum_{j=i}^L \alpha_j \rho_j + \beta_i \right) \right\}, & 0 \leq \prod_{i=1}^L \omega_i < 1, \end{cases} \quad (3.2a)$$

$$\begin{aligned} \gamma_L &= \omega_L + (1 - \omega_1) \left(1 + \sum_{i=1}^L \rho_i - 2 \sum_{i=1}^L \alpha_i \rho_i \right)^{\frac{2-p}{2}} \\ &+ \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left(1 + \sum_{j=i}^L \rho_j - 2 \sum_{j=i}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}}. \end{aligned} \quad (3.2b)$$

If the measurement matrix Φ satisfies RIP and

$$\delta_{tk} < \delta(t, p, \Theta), \quad (3.3)$$

where $d < t \leq 2d$, and for

$$\Theta = \frac{\gamma_L^{2/(2-p)}}{t-d} > 0, \quad (3.4)$$

$\delta(t, p, \Theta)$ is defined by

$$\delta(t, p, \Theta) = \begin{cases} \frac{1}{\sqrt{p^2 + (2-p)^2 \Theta - (1-p)}}, & \Theta \geq \Theta_0 = \frac{2+p}{2-p}, \\ \frac{z_0}{(2-p)\Theta - z_0}, & \Theta < \Theta_0, \end{cases} \quad (3.5)$$

where $z_0 \in ((1-p)\Theta, \min(1, \frac{2-p}{2}\Theta))$ is the only positive solution of the equation

$$\frac{p}{2} z^{\frac{2}{p}} + z - \frac{2-p}{2} \Theta = 0, \quad (3.6)$$

and

$$\delta(t, p, \Theta) = 1 \quad \text{if } \Theta = \frac{\gamma_L^{2/(2-p)}}{t-d} = 0,$$

then the weighted ℓ_p -minimization (1.2) recovers x exactly.

As $p = 1$, Theorem 3.1 presents a sufficient condition of the weighted ℓ_1 -minimization (1.3) for the exact recovery of x , which improves the theory of [17]. See the following Corollary 3.1.

Corollary 3.1. *If $p = 1$ and Φ satisfies RIP with*

$$\delta_{tk} < \frac{1}{\sqrt{1+\Theta}}, \quad (3.7)$$

where $d < t \leq 2d$ and

$$\Theta = (t-d)^{-1} \left(\omega_L + (1-\omega_1) \sqrt{1 + \sum_{i=1}^L \rho_i - 2 \sum_{i=1}^L \alpha_i \rho_i} + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \sqrt{1 + \sum_{j=i}^L \rho_j - 2 \sum_{j=i}^L \alpha_j \rho_j} \right)^2,$$

then the weighted ℓ_1 -minimization (1.3) exactly recover \mathbf{x} .

Remark 3.1. Note that the sufficient condition (3.7) is identical to the condition (3.1) in [8], since

$$\delta_{tk} < \frac{1}{\sqrt{1+\Theta}} = \sqrt{\frac{t-d}{t-d+\gamma_L^2}},$$

where the equality is from $\Theta = \frac{\gamma_L^2}{t-d}$ and

$$\begin{aligned} \gamma_L = & \omega_L + (1-\omega_1) \sqrt{1 + \sum_{i=1}^L \rho_i - 2 \sum_{i=1}^L \alpha_i \rho_i} \\ & + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \sqrt{1 + \sum_{j=i}^L \rho_j - 2 \sum_{j=i}^L \alpha_j \rho_j}. \end{aligned} \quad (3.8)$$

In noisy case, we have the following theorem.

Theorem 3.2. For $0 < p \leq 1$ and $\mathbf{y} = \Phi \mathbf{x} + \mathbf{e}$, suppose that $\hat{\mathbf{x}}$ is a minimizer of the weighted ℓ_p -minimization (1.2) with $\|\mathbf{e}\|_2 \leq \varepsilon$. If Φ satisfies RIP with

$$\delta_{tk} < \delta(t, p, \Theta) \quad (3.9)$$

for some $d < t \leq 2d$, where $\delta(t, p, \Theta)$ is defined in (3.5) for $\Theta > 0$. Then

$$\begin{aligned} & \|\mathbf{x} - \hat{\mathbf{x}}\|_2 \\ \leq & \sqrt{2} \cdot \left[\frac{4(2-p)\eta(1-\eta)\sqrt{1+\delta_{tk}} + 2\eta\sqrt{2(2-p)(1-p)(2-p-\eta)(\delta(t, p, \Theta) - \delta_{tk})}}{(2-p)(2-p-\eta)(\delta(t, p, \Theta) - \delta_{tk})} \right] \varepsilon, \end{aligned}$$

where

$$\eta = \begin{cases} \frac{2-p}{\sqrt{p^2 + (2-p)^2\Theta} + p}, & \Theta \geq \Theta_0 = \frac{2+p}{2-p}, \\ \frac{z_0}{\Theta}, & \Theta < \Theta_0, \end{cases} \quad (3.10)$$

and γ_L, z_0 are defined as in Theorem 3.1.

4 Proofs of the main results

4.1 Sparse representation and technical lemmas

The original work in [2] triggers an RIP analysis for signal recovery via l_1 minimization. The RIP analysis in [1] and [22] attains the summit for sparse signal recovery via l_1 minimization. The results in [1] and [22] depend on a key tool established in [20] and [1] independently, which represents points in a polytope

$$V = \{v \in \mathbb{R}^n, \|v\|_1 \leq k\alpha, \|v\|_\infty \leq \alpha \text{ for some } \alpha > 0\}$$

by convex combinations of k -sparse vectors. Zhang and Li [21] developed the tool, which extends the sparse representation of a polytope in [1] and [20] adapted to l_p , ($0 < p \leq 1$) case.

Lemma 4.1 ([21, Lemma 2.2]). *For $x \in \mathbb{R}^n$ which satisfies $|\text{supp}(x)| = K$, $\|x\|_p^p \leq L\rho^p$ and $\|x\|_\infty \leq \rho$ with $L \leq K$ being a positive integer, ρ being a positive constant and $0 < p \leq 1$, then x can be represented as the convex combination of L -sparse vectors, i.e.,*

$$x = \sum_i \lambda_i u_i,$$

where $\lambda_i > 0$, $\sum_i \lambda_i = 1$ and $\|u_i\|_0 \leq L$. Furthermore,

$$\sum_i \lambda_i \|u_i\|_2^2 \leq \min \left\{ \frac{n}{L} \|x\|_2^2, \rho^p \|x\|_{2-p}^{2-p} \right\}. \tag{4.1}$$

For the weighted ℓ_p -minimization (1.2) with L distinct weights, the cone constraint inequality can be stated as follows.

Lemma 4.2. *If $\|\hat{x}\|_{p,w}^p \leq \|x\|_{p,w}^p$ and $h = \hat{x} - x$, then for any index set $\Gamma \subseteq [n]$,*

$$\begin{aligned} \|h_{\Gamma^c}\|_p^p &\leq \omega_L \|h_\Gamma\|_p^p + (1 - \omega_1) \|h_{(\Gamma \cup \cup_{i=1}^L \tilde{T}_i) \setminus (\cup_{i=1}^L \tilde{T}_i \cap \Gamma)}\|_p^p \\ &\quad + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \|h_{(\Gamma \cup \cup_{i=j}^L \tilde{T}_i) \setminus (\cup_{i=j}^L \tilde{T}_i \cap \Gamma)}\|_p^p \\ &\quad + 2 \left(\omega \|x_{\Gamma^c}\|_p^p + (1 - \omega) \|x_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|x_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right), \end{aligned} \tag{4.2}$$

where

$$\tilde{T} = \cup_{i=1}^L \tilde{T}_i \quad \text{and} \quad \omega = \sum_{i=1}^L \omega_i.$$

Proof. By $\hat{x} = x + h$ and the choice of the weights in (3.1),

$$\|\hat{x}\|_{p,w}^p = \|x + h\|_{p,w}^p \leq \|x\|_{p,w}^p$$

implies

$$\sum_{i=1}^L \omega_i \|\mathbf{x}_{\tilde{T}_i} + \mathbf{h}_{\tilde{T}_i}\|_p^p + \|\mathbf{x}_{\tilde{T}^c} + \mathbf{h}_{\tilde{T}^c}\|_p^p \leq \sum_{i=1}^L \omega_i \|\mathbf{x}_{\tilde{T}_i}\|_p^p + \|\mathbf{x}_{\tilde{T}^c}\|_p^p.$$

Furthermore, we have

$$\begin{aligned} & \sum_{i=1}^L (\omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma} + \mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c} + \mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p) \\ & \quad + \|\mathbf{x}_{\tilde{T}^c \cap \Gamma} + \mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p + \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c} + \mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \\ & \leq \sum_{i=1}^L (\omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma}\|_p^p + \omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c}\|_p^p) + \|\mathbf{x}_{\tilde{T}^c \cap \Gamma}\|_p^p + \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c}\|_p^p. \end{aligned}$$

Next, we use the reverse triangle inequality to get

$$\begin{aligned} & \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \\ & \leq \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p + 2 \left(\sum_{i=1}^L \omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \right). \end{aligned} \quad (4.3)$$

Now, we can write

$$\|\mathbf{h}_{\Gamma^c}\|_p^p = \sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p.$$

Let us add and subtract $\omega_i \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p$ for all pairs of i and j such that $i, j = 1, \dots, L$ and $i \neq j$, and $\omega_i \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p$ for $i = 1, \dots, L$ to the left side of (4.3). Then the left side of (4.3) becomes

$$\begin{aligned} & \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p + \sum_{i,j,i \neq j} \omega_i \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p - \sum_{i \neq j} \omega_i \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p \\ & \quad + \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \\ & = \sum_{i=1}^L \omega_i \left(\|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \sum_{j \neq i} \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p \right) - \sum_{i \neq j} \omega_i \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p + \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \\ & = \omega \|\mathbf{h}_{\Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{j=1}^L \left(\sum_{i \neq j} \omega_i \right) \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p \\ & = \omega \|\mathbf{h}_{\Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{j=1}^L (\omega - \omega_j) \|\mathbf{h}_{\tilde{T}_j \cap \Gamma^c}\|_p^p. \end{aligned}$$

Similarly, we can write

$$\|\mathbf{h}_\Gamma\|_p^p = \sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p.$$

Let us add and subtract $\omega_i \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p$ for all pairs of i and j such that $i, j = 1, \dots, L$ and $i \neq j$, and $\omega_i \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p$ for $i = 1, \dots, L$ to the right side of (4.3), as well as $\omega_i \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c}\|_p^p$ for $i = 1, \dots, L$ and $i \neq j$, and $\omega_i \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c}\|_p^p$ for $i = 1, \dots, L$. Then the right side of (4.3) becomes

$$\begin{aligned} & \omega \|\mathbf{h}_\Gamma\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p \\ & + 2 \left(\omega \|\mathbf{x}_{\Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right). \end{aligned}$$

Let

$$D = \omega \|\mathbf{x}_{\Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{x}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{x}_{\tilde{T}_i \cap \Gamma^c}\|_p^p.$$

Putting these together, we have

$$\begin{aligned} & \omega \|\mathbf{h}_{\Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p \\ & \leq \omega \|\mathbf{h}_\Gamma\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + 2D. \end{aligned} \tag{4.4}$$

But, we can also write $\|\mathbf{h}_{\Gamma^c}\|_p^p$ as

$$\|\mathbf{h}_{\Gamma^c}\|_p^p = \omega \|\mathbf{h}_{\Gamma^c}\|_p^p + \sum_{i=1}^L (1 - \omega) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p.$$

Solving for $\omega \|\mathbf{h}_{\Gamma^c}\|_p^p$ and substituting into (4.4) gives

$$\begin{aligned} & \|\mathbf{h}_{\Gamma^c}\|_p^p - \sum_{i=1}^L (1 - \omega) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p - (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p \\ & + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma^c}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p \\ & \leq \omega \|\mathbf{h}_\Gamma\|_p^p + (1 - \omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + 2D. \end{aligned}$$

Simplifying, we get

$$\begin{aligned}
\|\mathbf{h}_{\Gamma^c}\|_p^p &\leq \sum_{i=1}^L (1-\omega) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \omega \|\mathbf{h}_{\Gamma}\|_p^p \\
&\quad + (1-\omega) \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L (\omega - \omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + 2D \\
&= \sum_{i=1}^L (1-\omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \omega \|\mathbf{h}_{\Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p \\
&\quad - \sum_{i=1}^L \omega_i \left(\|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p + \sum_{j=1, j \neq i}^L \|\mathbf{h}_{\tilde{T}_j \cap \Gamma}\|_p^p \right) + 2D \\
&= \sum_{i=1}^L (1-\omega_i) \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \omega \|\mathbf{h}_{\Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L \omega_i \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p \\
&\quad + \sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p - \sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + 2D \tag{4.5}
\end{aligned}$$

$$\begin{aligned}
&= \omega \|\mathbf{h}_{\Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p - \sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \sum_{i=1}^L (1-\omega_i) \left(\|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p \right) + 2D \\
&= (\omega - (L-1)) \|\mathbf{h}_{\Gamma}\|_p^p + \sum_{i=1}^L (1-\omega_i) \left(\|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p \right) + 2D, \tag{4.6}
\end{aligned}$$

where in (4.5) we have added zero and observed that

$$\|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p + \sum_{j=1, j \neq i}^L \|\mathbf{h}_{\tilde{T}_j \cap \Gamma}\|_p^p = \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p$$

and in (4.6), we have observed that

$$\sum_{i=1}^L \|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p = (L-1) \|\mathbf{h}_{\Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}^c \cap \Gamma}\|_p^p.$$

Then assuming, without loss of generality, $\omega_1 \geq \omega_2 \geq \dots \geq \omega_L$, and writing $1 - \omega_i = 1 - \omega_1 + \omega_1 - \omega_i$ for $i > 1$, we have

$$\begin{aligned}
\|\mathbf{h}_{\Gamma^c}\|_p^p &\leq (\omega - (L-1)) \|\mathbf{h}_{\Gamma}\|_p^p + (1-\omega_1) \sum_{i=1}^L \left(\|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) \\
&\quad + \sum_{i=2}^L (\omega_1 - \omega_i) \left(\|\mathbf{h}_{\tilde{T}_i \cap \Gamma}\|_p^p + \|\mathbf{h}_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) + 2D. \tag{4.7}
\end{aligned}$$

Next, write $\omega_1 - \omega_i = \omega_1 - \omega_2 + \omega_2 - \omega_i$ for $i > 2$. Then we have

$$\begin{aligned} \|h_{\Gamma^c}\|_p^p &\leq (\omega - (L - 1))\|h_{\Gamma}\|_p^p + (1 - \omega_1) \sum_{i=1}^L \left(\|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p + \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) + (\omega_1 - \omega_2) \\ &\quad \times \sum_{i=2}^L \left(\|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p + \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) + \sum_{i=3}^L (\omega_2 - \omega_i) \left(\|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p + \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) \\ &\quad + 2D. \end{aligned} \tag{4.8}$$

Continuing in this way gives us

$$\begin{aligned} \|h_{\Gamma^c}\|_p^p &\leq (\omega - (L - 1))\|h_{\Gamma}\|_p^p + (1 - \omega_1) \sum_{i=1}^L \left(\|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p + \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) \\ &\quad + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \sum_{i=j}^L \left(\|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p + \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p \right) + 2D. \end{aligned} \tag{4.9}$$

Noting

$$\begin{aligned} \|h_{\tilde{T}_i^c \cap \Gamma}\|_p^p &= \sum_{j=1, j \neq i}^L \|h_{\tilde{T}_j \cap \Gamma}\|_p^p + \|h_{\Gamma \cap \cap_{j=1}^L \tilde{T}_j^c}\|_p^p, \\ \|h_{\Gamma}\|_p^p &= \sum_{i=1}^L \|h_{\tilde{T}_i \cap \Gamma}\|_p^p + \|h_{\Gamma \cap \cap_{j=1}^L \tilde{T}_j^c}\|_p^p, \\ \sum_{i=j}^L \|h_{\tilde{T}_i \cap \Gamma^c}\|_p^p + \|h_{\Gamma \cap \cap_{i=j}^L \tilde{T}_i^c}\|_p^p &= \|h_{\Gamma \cup \cup_{i=j}^L \tilde{T}_i \setminus \cup_{i=j}^L (\tilde{T}_i \cap \Gamma)}\|_p^p, \end{aligned}$$

for any $j = 1, 2, \dots, L$, the above inequality can also be expressed as

$$\begin{aligned} \|h_{\Gamma^c}\|_p^p &\leq (\omega - (L - 1))\|h_{\Gamma}\|_p^p + (1 - \omega_1) \left((L - 1)\|h_{\Gamma}\|_p^p + \|h_{\Gamma \cup \cup_{i=1}^L \tilde{T}_i \setminus \cup_{i=1}^L (\tilde{T}_i \cap \Gamma)}\|_p^p \right) \\ &\quad + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \left((L - j)\|h_{\Gamma}\|_p^p + \|h_{\Gamma \cup \cup_{i=j}^L \tilde{T}_i \setminus \cup_{i=j}^L (\tilde{T}_i \cap \Gamma)}\|_p^p \right) + 2D. \end{aligned} \tag{4.10}$$

Combining the coefficients of $\|h_{\Gamma}\|_p^p$, we have

$$\begin{aligned} &\sum_{i=1}^L \omega_i - (L - 1) + (1 - \omega_1)(L - 1) + \sum_{j=2}^L (\omega_{j-1} - \omega_j)(L - j) \\ &= \sum_{i=1}^L \omega_i - (L - 1)\omega_1 + (L - 2)\omega_1 + \sum_{j=2}^{L-1} (L - (j + 1))\omega_j - \sum_{j=2}^{L-1} (L - j)\omega_j \\ &= \sum_{i=2}^L \omega_i - \sum_{j=2}^{L-1} \omega_j = \omega_L. \end{aligned}$$

Finally, we obtain that

$$\begin{aligned} \|\mathbf{h}_{\Gamma^c}\|_p^p &\leq \omega_L \|\mathbf{h}_\Gamma\|_p^p + (1 - \omega_1) \|\mathbf{h}_{\Gamma \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap \Gamma)}\|_p^p \\ &\quad + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \|\mathbf{h}_{\Gamma \cup \bigcup_{i=j}^L \tilde{T}_i \setminus \bigcup_{i=j}^L (\tilde{T}_i \cap \Gamma)}\|_p^p + 2D. \end{aligned}$$

Thus, we complete the proof. \square

The following two technical lemmas will be used to simplify the proof of our main results.

Lemma 4.3 ([9, Lemma V.1]). *Let p and q be two positive numbers. Then*

- (a) $\|\mathbf{x}\|_p \leq \|\mathbf{x}\|_2 |\text{supp}(\mathbf{x})|^{\frac{2-p}{2p}}$, if $0 < p < 2$,
- (b) $\|\mathbf{x}\|_p^p \leq (\|\mathbf{x}\|_2^2)^{\frac{1}{q}} (\|\mathbf{x}\|_{p_1}^{p_1})^{1-\frac{1}{q}}$, if $pq > 2$ and $q > 1$, where $p_1 = (p - \frac{2}{q})(\frac{q}{q-1})$.

Lemma 4.4 ([9, Lemma V.2]). *For $0 < p \leq 1$ and $\Lambda > 0$, the function*

$$g(z) = \frac{p}{2} z^{\frac{2}{p}} + z - \frac{2-p}{2} \Lambda$$

is monotone increasing in $(0, \infty)$. In addition, the following statements hold:

- (I) *If $0 < \Lambda \leq \frac{2}{2-p}$, there exists a unique point $z_0 \in ((1-p)\Lambda, (1-\frac{p}{2})\Lambda) \subseteq (0, 1)$ such that $g(z_0) = 0$.*
- (II) *If $\frac{2}{2-p} < \Lambda < \frac{2+p}{2-p}$, there exists a unique point $z_0 \in ((1-p)\Lambda, 1) \subseteq (0, 1)$ such that $g(z_0) = 0$.*
- (III) *If $\Lambda \geq \frac{2+p}{2-p}$, there does not exist a point $z_0 \in (0, 1)$ such that $g(z_0) = 0$.*

4.2 Proof of Theorem 3.1

Proof. We assume that tk is an integer. When tk is not an integer, it can be treated as in [1] and [9]. Let $\mathbf{h} = \hat{\mathbf{x}} - \mathbf{x}$, where $\hat{\mathbf{x}}$ is a minimizer of the weighted ℓ_p -minimization problem (1.2) with $\epsilon = 0$. Then

$$\Phi \mathbf{h} = \mathbf{0}. \quad (4.11)$$

We prove $\mathbf{h} = \mathbf{0}$ to show that \mathbf{x} could be recovered exactly via the weighted ℓ_p -minimization (1.2).

On the contrary, we suppose here that $\mathbf{h} \neq \mathbf{0}$, then $\mathbf{h}_{\max(dk)} \neq \mathbf{0}$, where $\mathbf{h}_{\max(dk)}$ is the best dk -term approximation of \mathbf{h} and we define

$$\mathbf{h}_{-\max(dk)} = \mathbf{h} - \mathbf{h}_{\max(dk)}.$$

Since T is the support set of the k -sparse vector \mathbf{x} , we know that $|T| \leq k$. Recall the definition of d in (3.2a),

$$d = \begin{cases} 1, & \omega_1 = \dots = \omega_L = 1, \\ \max_{i \in \{1, 2, \dots, L\}} \left\{ b_i \left(1 - \sum_{j=i}^L \alpha_j \rho_j + \beta_i \right) \right\}, & 0 \leq \prod_{i=1}^L \omega_i < 1, \end{cases} \tag{4.12}$$

where

$$\beta_i = \max \left\{ \sum_{j=i}^L \alpha_j \rho_j, \sum_{j=i}^L (1 - \alpha_j) \rho_j \right\},$$

$$b_i = \begin{cases} 1, & i = 1, \\ \text{sgn}(\omega_{i-1} - \omega_i), & i = 2, \dots, L. \end{cases}$$

It is clear that $d \geq 1$ and dk is an integer. Thus,

$$\begin{aligned} & \|\mathbf{h}_{-\max(dk)}\|_p^p \leq \|\mathbf{h}_{T^c}\|_p^p \\ & \leq \omega_L \|\mathbf{h}_T\|_p^p + (1 - \omega_1) \|\mathbf{h}_{T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap T)}\|_p^p \\ & \quad + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \|\mathbf{h}_{T \cup \bigcup_{i=j}^L \tilde{T}_i \setminus \bigcup_{i=j}^L (\tilde{T}_i \cap T)}\|_p^p \end{aligned} \tag{4.13}$$

$$\leq \begin{cases} \|\mathbf{h}_T\|_p^p, & \omega_1 = \dots = \omega_L = 1, \\ \omega_L \|\mathbf{h}_T\|_p^p + (1 - \omega_L) \|\mathbf{h}_{\max(dk)}\|_p^p, & 0 \leq \prod_{i=1}^L \omega_i < 1, \end{cases} \tag{4.14}$$

where the first inequality is from $d \geq 1$ and $|T| \leq k$, the second inequality follows from Lemma 4.2 with $\Gamma = T$ and the last inequality is due to

$$\left| \left(T \cup \bigcup_{j=i}^L \tilde{T}_j \right) \setminus \bigcup_{j=i}^L (T \cap \tilde{T}_j) \right| \leq k + \sum_{j=i}^L \rho_j k - 2 \sum_{j=i}^L \alpha_j \rho_j k = k \left(1 + \sum_{j=i}^L \rho_j - 2 \sum_{j=i}^L \alpha_j \rho_j \right) \leq dk$$

with

$$\beta_i = \max \left\{ \sum_{j=i}^L \alpha_j \rho_j, \sum_{j=i}^L (1 - \alpha_j) \rho_j \right\}.$$

Let

$$v = \left(\frac{\omega_L \|\mathbf{h}_T\|_p^p + (1 - \omega_1) \|\mathbf{h}_{T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap T)}\|_p^p + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \|\mathbf{h}_{T \cup \bigcup_{i=j}^L \tilde{T}_i \setminus \bigcup_{i=j}^L (\tilde{T}_i \cap T)}\|_p^p}{k(t - d)} \right)^{\frac{1}{p}}. \tag{4.15}$$

Then $v \geq 0$. First, we suppose that $v = 0$, then we have $\|\mathbf{h}_{T^c}\|_p^p = 0$ by (4.13), which implies \mathbf{h} is k -sparse. Since the sensing matrix Φ satisfies the RIP of order tk with $t > d \geq 1$ and (4.11), we have $\mathbf{h} = \mathbf{0}$. Therefore, \mathbf{x} is exactly recovered by (1.2) with $\epsilon = 0$.

For $\nu > 0$, we divide the vector $\mathbf{h}_{-\max(dk)}$ into two parts, i.e.,

$$\mathbf{h}_{-\max(dk)} = \mathbf{h}^{(1)} + \mathbf{h}^{(2)}, \quad (4.16)$$

where

$$\mathbf{h}^{(1)} = \mathbf{h}_{-\max(dk)} \cdot \chi_{\{i \mid |\mathbf{h}_{-\max(dk)}(i)| > \nu\}}, \quad (4.17a)$$

$$\mathbf{h}^{(2)} = \mathbf{h}_{-\max(dk)} \cdot \chi_{\{i \mid |\mathbf{h}_{-\max(dk)}(i)| \leq \nu\}}. \quad (4.17b)$$

Then

$$\|\mathbf{h}^{(1)}\|_p^p \leq \|\mathbf{h}_{-\max(dk)}\|_p^p \leq k(t-d)\nu^p$$

by (4.13) and (4.15). Denote $|\text{supp}(\mathbf{h}^{(1)})| = \|\mathbf{h}^{(1)}\|_0 = m$. Since all non-zero entries of $\mathbf{h}^{(1)}$ have absolute value larger than ν , we have

$$(t-d)k\nu^p \geq \|\mathbf{h}_{-\max(dk)}\|_p^p \geq \|\mathbf{h}^{(1)}\|_p^p = \sum_{i \in \text{supp}(\mathbf{h}^{(1)})} |\mathbf{h}^{(1)}(i)|^p \geq m\nu^p. \quad (4.18)$$

By (4.18) and $\nu \neq 0$, one has

$$|\text{supp}(\mathbf{h}^{(1)})| = m \leq (t-d)k$$

and

$$|\text{supp}(\mathbf{h}_{\max(dk)}) + \text{supp}(\mathbf{h}^{(1)})| \leq dk + |\text{supp}(\mathbf{h}^{(1)})| \leq dk + (t-d)k = tk. \quad (4.19)$$

Moreover,

$$\|\mathbf{h}^{(2)}\|_\infty \stackrel{(a)}{\leq} \nu, \quad \|\mathbf{h}^{(2)}\|_p^p \stackrel{(b)}{=} \|\mathbf{h}_{-\max(dk)}\|_p^p - \|\mathbf{h}^{(1)}\|_p^p \stackrel{(c)}{\leq} ((t-d)k - m)\nu^p, \quad (4.20)$$

where (a) is from (4.17b), (b) is due to (4.16) and (c) follows from (4.18). Applying Lemma 4.1 with $L = k(t-d) - m$ and $\rho = \nu$, we can express $\mathbf{h}^{(2)}$ as a convex combination of $(k(t-d) - m)$ -sparse vectors, i.e., $\mathbf{h}^{(2)} = \sum_i \lambda_i \mathbf{u}_i$, where $\lambda_i > 0$, $\sum_i \lambda_i = 1$, \mathbf{u}_i is $(k(t-d) - m)$ -sparse and $\text{supp}(\mathbf{u}_i) \subseteq \text{supp}(\mathbf{h}^{(2)})$. By (4.16), we have

$$\langle \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}, \mathbf{u}_i \rangle = 0. \quad (4.21)$$

Furthermore, by (4.1),

$$\begin{aligned} \sum_i \lambda_i \|\mathbf{u}_i\|_2^2 &\leq \min \left\{ \frac{n}{L} \|\mathbf{h}^{(2)}\|_2^2, \nu^p \|\mathbf{h}^{(2)}\|_{2-p}^{2-p} \right\} \leq \nu^p \|\mathbf{h}^{(2)}\|_{2-p}^{2-p} \\ &\leq \nu^p (\|\mathbf{h}^{(2)}\|_2^2)^{\frac{2-2p}{2-p}} (\|\mathbf{h}^{(2)}\|_p^p)^{\frac{p}{2-p}} \\ &\leq \nu^p (\|\mathbf{h}^{(2)}\|_2^2)^{\frac{2-2p}{2-p}} \left(((t-d)k - m)\nu^p \right)^{\frac{p}{2-p}} \\ &\leq (\|\mathbf{h}^{(2)}\|_2^2)^{\frac{2-2p}{2-p}} \left(k(t-d)\nu^2 \right)^{\frac{p}{2-p}}, \end{aligned} \quad (4.22)$$

where the third inequality is from Lemma 4.3(b), and the fourth inequality follows from (4.20). By (4.15), we have

$$\begin{aligned}
 & k(t-d)v^2 \\
 &= (k(t-d))^{1-\frac{2}{p}} \left(\omega_L \|\mathbf{h}_T\|_p^p + (1-\omega_1) \|\mathbf{h}_{T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap T)}\|_p^p \right. \\
 &\quad \left. + \sum_{j=2}^L (\omega_{j-1} - \omega_j) \|\mathbf{h}_{T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap T)}\|_p^p \right)^{\frac{2}{p}} \\
 &\leq (k(t-d))^{1-\frac{2}{p}} \left(\omega_L |T|^{\frac{2-p}{2}} \|\mathbf{h}_T\|_p^p \right. \\
 &\quad \left. + (1-\omega_1) \left| T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{i=1}^L (\tilde{T}_i \cap T) \right|^{\frac{2-p}{2}} \|\mathbf{h}_T\|_p^p + (1-\omega_1) \|\mathbf{h}_{T \cup \bigcup_{i=1}^L \tilde{T}_i \setminus \bigcup_{j=i}^L (\tilde{T}_j \cap T)}\|_2^2 \right. \\
 &\quad \left. + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left| \bigcup_{j=i}^L \tilde{T}_i \setminus \bigcup_{j=i}^L (\tilde{T}_j \cap T) \right|^{\frac{2-p}{2}} \|\mathbf{h}_T\|_p^p + (1-\omega_1) \|\mathbf{h}_{T \cup \bigcup_{j=i}^L \tilde{T}_j \setminus \bigcup_{j=i}^L (\tilde{T}_j \cap T)}\|_2^2 \right)^{\frac{2}{p}} \\
 &\leq (k(t-d))^{1-\frac{2}{p}} k^{\frac{2-p}{p}} \left(\omega_L + (1-\omega_1) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right. \\
 &\quad \left. + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right)^{\frac{2}{p}} \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2 \\
 &= (t-d)^{1-\frac{2}{p}} \left(\omega_L + (1-\omega_1) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right. \\
 &\quad \left. + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right)^{\frac{2}{p}} \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2, \tag{4.23}
 \end{aligned}$$

where the first inequality is due to $0 < p \leq 1$ and Lemma 4.3(a) and the second inequality is from $|T| \leq k$ and

$$\begin{aligned}
 & \left| T \cup \bigcup_{j=i}^L \tilde{T}_j \setminus \bigcup_{j=i}^L (T \cap \tilde{T}_j) \right| \\
 &= k + \sum_{j=i}^L \rho_j k - 2 \sum_{j=i}^L \alpha_j \rho_j k = k \left(1 + \sum_{j=i}^L \rho_j - 2 \sum_{j=i}^L \alpha_j \rho_j \right) \leq dk.
 \end{aligned}$$

Then, by (4.22) and (4.23),

$$\begin{aligned}
 \sum_i \lambda_i \|\mathbf{u}_i\|_2^2 &\leq (\|\mathbf{h}^{(2)}\|_2^2)^{\frac{2-2p}{2-p}} (t-d)^{-1} \left(\omega_L + (1-\omega_1) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right. \\
 &\quad \left. + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right)^{\frac{2}{2-p}} (\|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2)^{\frac{p}{2-p}}
 \end{aligned}$$

$$= \Theta \mu^{\frac{2-2p}{2-p}} \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2, \tag{4.24}$$

where the equality is due to (3.4) and

$$\mu = \frac{\|\mathbf{h}^{(2)}\|_2^2}{\|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2}. \tag{4.25}$$

We have $0 \leq \mu \leq 1$ since

$$\begin{aligned} \|\mathbf{h}^{(2)}\|_2^2 &\leq \|\mathbf{h}^{(2)}\|_\infty^{2-p} \|\mathbf{h}^{(2)}\|_p^p \\ &\leq \|\mathbf{h}^{(2)}\|_\infty^{2-p} \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_p^p \\ &\leq \min_{i \in \text{supp}(\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)})} |h_i|^{2-p} \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_p^p \\ &\leq \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2, \end{aligned}$$

where the second inequality is from (4.14), $|T| \leq k \leq dk$ with $d \geq 1$.

For $\eta \in \mathbb{R}$, let

$$\boldsymbol{\theta}_i = \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} + \eta \mathbf{u}_i,$$

then

$$\begin{aligned} \sum_j \lambda_j \boldsymbol{\theta}_j - \frac{p}{2} \boldsymbol{\theta}_i &= \left(1 - \frac{p}{2}\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) + \eta \sum_j \lambda_j \mathbf{u}_j - \frac{p}{2} \eta \mathbf{u}_i \\ &\stackrel{(a)}{=} \left(1 - \frac{p}{2}\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) + \eta \mathbf{h}^{(2)} - \frac{p}{2} \eta \mathbf{u}_i \\ &\stackrel{(b)}{=} \left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) + \eta \mathbf{h} - \frac{p}{2} \eta \mathbf{u}_i, \end{aligned} \tag{4.26}$$

i.e.,

$$\sum_j \lambda_j \boldsymbol{\theta}_j - \frac{p}{2} \boldsymbol{\theta}_i - \eta \mathbf{h} = \left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) - \frac{p}{2} \eta \mathbf{u}_i,$$

where (a) is due to $\mathbf{h}^{(2)} = \sum_i \lambda_i \mathbf{u}_i$, and (b) is from

$$\mathbf{h} = \mathbf{h}_{\max(dk)} + \mathbf{h}_{\max(dk)^c} \quad \text{and} \quad \mathbf{h}_{\max(dk)^c} = \mathbf{h}^{(1)} + \mathbf{h}^{(2)}.$$

Due to

$$\|\mathbf{u}_i\|_0 \leq k(t-d) - |\text{supp}(\mathbf{h}^{(2)})|$$

and the definition of $\mathbf{h}_{\max(dk)}$, the vectors $\boldsymbol{\theta}_i$,

$$\sum_j \lambda_j \boldsymbol{\theta}_j - \frac{p}{2} \boldsymbol{\theta}_i - \eta \mathbf{h} \quad \text{and} \quad \left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) - \frac{p}{2} \eta \mathbf{u}_i$$

are all tk -sparse. By (4.11) and (4.26), we have

$$\begin{aligned} & \sum_i \lambda_i \left\| \Phi \left(\sum_j \lambda_j \theta_j - \frac{p}{2} \theta_i \right) \right\|_2^2 \\ &= \sum_i \lambda_i \left\| \Phi \left(\left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) - \frac{p}{2} \eta \mathbf{u}_i \right) \right\|_2^2 \\ &\leq (1 + \delta_{tk}) \sum_i \lambda_i \left\| \left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) - \frac{p}{2} \eta \mathbf{u}_i \right\|_2^2 \\ &= (1 + \delta_{tk}) \left[\left(1 - \frac{p}{2} - \eta\right)^2 \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2 + \frac{p^2 \eta^2}{4} \sum_i \lambda_i \|\mathbf{u}_i\|_2^2 \right], \end{aligned} \tag{4.27}$$

where the first inequality is from

$$\left(1 - \frac{p}{2} - \eta\right) (\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}) - \frac{p}{2} \eta \mathbf{u}_i$$

is tk -sparse and the last equality is due to (4.21). Since θ_i is a tk -sparse vectors, we have

$$\begin{aligned} & \frac{1-p}{2} \sum_{i,j} \lambda_i \lambda_j \|\Phi(\theta_i - \theta_j)\|_2^2 \\ &= \eta^2 \frac{1-p}{2} \sum_{i,j} \lambda_i \lambda_j \|\Phi(\mathbf{u}_i - \mathbf{u}_j)\|_2^2 \\ &\leq (1 + \delta_{tk}) \eta^2 \frac{1-p}{2} \sum_{i,j} \lambda_i \lambda_j \|\mathbf{u}_i - \mathbf{u}_j\|_2^2 \\ &= (1 + \delta_{tk}) \eta^2 (1-p) \left(\sum_i \lambda_i \|\mathbf{u}_i\|_2^2 - \left\| \sum_i \lambda_i \mathbf{u}_i \right\|_2^2 \right) \\ &= (1 + \delta_{tk}) \eta^2 (1-p) \left(\sum_i \lambda_i \|\mathbf{u}_i\|_2^2 - \|\mathbf{h}^{(2)}\|_2^2 \right), \end{aligned} \tag{4.28}$$

where the inequality is from that \mathbf{u}_i is $(k(t-d) - m)$ -sparse and $d < t \leq 2d$. $\mathbf{u}_i - \mathbf{u}_j$ is tk -sparse as $d < t \leq 2d$ since

$$tk - 2(k(t-d) - m) = k(2d - t) + m \geq 0.$$

Since θ_i is tk -sparse, it follows that

$$\begin{aligned} & \left(1 - \frac{p}{2}\right)^2 \sum_i \lambda_i \|\Phi \theta_i\|_2^2 \geq (1 - \delta_{tk}) \left(1 - \frac{p}{2}\right)^2 \sum_i \lambda_i \|\theta_i\|_2^2 \\ &= (1 - \delta_{tk}) \left(1 - \frac{p}{2}\right)^2 \left(\|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2 + \eta^2 \sum_i \lambda_i \|\mathbf{u}_i\|_2^2 \right), \end{aligned} \tag{4.29}$$

where the equality is from the definition of θ_i and (4.21).

By (4.27)-(4.29) and the following identity (see [21, (21)])

$$\begin{aligned} & \sum_i \lambda_i \left\| \Phi \left(\sum_j \lambda_j \theta_j - \frac{p}{2} \theta_i \right) \right\|_2^2 + \frac{1-p}{2} \sum_{i,j} \lambda_i \lambda_j \left\| \Phi(\gamma_i - \theta_j) \right\|_2^2 \\ & - \left(1 - \frac{p}{2}\right)^2 \sum_i \lambda_i \left\| \Phi \theta_i \right\|_2^2 = 0, \end{aligned} \quad (4.30)$$

we have

$$\begin{aligned} 0 & \leq (1 + \delta_{tk}) \left[\left(1 - \frac{p}{2} - \eta\right)^2 \left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2 \right. \\ & \quad \left. + \eta^2 \left(\frac{p^2}{4} + (1-p) \right) \sum_i \lambda_i \left\| \mathbf{u}_i \right\|_2^2 - \eta^2 (1-p) \left\| \mathbf{h}^{(2)} \right\|_2^2 \right] \\ & \quad - (1 - \delta_{tk}) \left(1 - \frac{p}{2}\right)^2 \left(\left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2 + \eta^2 \sum_i \lambda_i \left\| \mathbf{u}_i \right\|_2^2 \right) \\ & = (1 + \delta_{tk}) \left[\left(1 - \frac{p}{2} - \eta\right)^2 \left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2 - \eta^2 (1-p) \left\| \mathbf{h}^{(2)} \right\|_2^2 \right] \\ & \quad - (1 - \delta_{tk}) \left(1 - \frac{p}{2}\right)^2 \left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2 \\ & \quad + 2\delta_{tk} \left(1 - \frac{p}{2}\right)^2 \eta^2 \sum_i \lambda_i \left\| \mathbf{u}_i \right\|_2^2. \end{aligned}$$

From (4.25), (4.24) and the above inequality, it follows that

$$\begin{aligned} 0 & \leq \left((1 + \delta_{tk}) \left(\left(1 - \frac{p}{2} - \eta\right)^2 - \eta^2 (1-p) \mu \right) - (1 - \delta_{tk}) \left(1 - \frac{p}{2}\right)^2 \right. \\ & \quad \left. + 2\delta_{tk} \left(1 - \frac{p}{2}\right)^2 \eta^2 \Theta \mu^{\frac{2-2p}{2-p}} \right) \left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2 \\ & = \left[(\eta^2 - (2-p)\eta - \eta^2(1-p)\mu) + \delta_{tk} \left(\left(1 - \frac{p}{2} - \eta\right)^2 + \left(1 - \frac{p}{2}\right)^2 \right. \right. \\ & \quad \left. \left. + 2 \left(1 - \frac{p}{2}\right)^2 \eta^2 \Theta \mu^{\frac{2-2p}{2-p}} - \eta^2(1-p)\mu \right) \right] \left\| \mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} \right\|_2^2. \end{aligned} \quad (4.31)$$

Next, let the arbitrary vector η satisfies

$$\eta = \frac{2-p}{\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}} + 1 - (1-p)\mu}}. \quad (4.32)$$

By $0 < p \leq 1$ and $0 \leq \mu \leq 1$, it is clear that $0 < \eta < \frac{2-p}{1-(1-p)\mu}$. Moreover, we have

$$\begin{aligned} \eta^2 - (2-p)\eta - \eta^2(1-p)\mu & = \eta^2 \left(1 - (1-p)\mu - (2-p) \frac{1}{\eta} \right) \\ & \stackrel{(a)}{=} -\eta^2 \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} \end{aligned}$$

and

$$\begin{aligned} & \left(1 - \frac{p}{2} - \eta\right)^2 + \left(1 - \frac{p}{2}\right)^2 + 2\left(1 - \frac{p}{2}\right)^2 \eta^2 \Theta \mu^{\frac{2-2p}{2-p}} - \eta^2(1-p)\mu \\ &= \eta^2 \left(1 - (1-p)\mu + \frac{1}{2}(2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}} + \frac{(2-p)^2}{2\eta^2} - (2-p)\frac{1}{\eta}\right) \\ &\stackrel{(b)}{=} \eta^2 \left(1 - (1-p)\mu + \frac{1}{2}(2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}} + \frac{1}{2} \left(\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} \right. \right. \\ &\quad \left. \left. + 1 - (1-p)\mu\right)^2 - \left(\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} + 1 - (1-p)\mu\right)\right) \\ &= \eta^2 \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} \left(\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} - (1-p)\mu\right), \end{aligned}$$

where (a) and (b) are from (4.32). Therefore, from (4.31), it follows that

$$\begin{aligned} & -\eta^2 \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} \left[1 - \delta_{tk} \left(\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} \right. \right. \\ & \quad \left. \left. - (1-p)\mu\right)\right] \|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2^2 \geq 0. \end{aligned} \tag{4.33}$$

Define a function

$$f(\mu) = \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}} - (1-p)\mu,$$

where $0 \leq \mu \leq 1$. If $\Theta = 0$, then $f(\mu) = 1 - 2(1-p)\mu \leq 1$. In this case, (4.33) is a contradiction from $\delta_{tk} < 1$. In the following, we assume that $\Theta > 0$. By some elementary calculation, we have

$$\begin{aligned} f'(\mu) &= \frac{-2(1-p)(2-p)\Theta \mu^{-\frac{2p}{2-p}}}{\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}}} \\ &\quad \cdot \left[\frac{\frac{p}{2} \mu^{\frac{p}{2-p} \cdot \frac{2}{p}} + \mu^{\frac{p}{2-p}} - \frac{2-p}{2} \Theta}{(-1 + (1-p)\mu) + (2-p)\Theta \mu^{\frac{-p}{2-p}} + \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}}} \right] \\ &= \frac{-2(1-p)(2-p)\Theta \mu^{-\frac{2p}{2-p}}}{\sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}}} \\ &\quad \cdot \left[\frac{g(\mu^{\frac{p}{2-p}})}{(-1 + (1-p)\mu) + (2-p)\Theta \mu^{\frac{-p}{2-p}} + \sqrt{(1 - (1-p)\mu)^2 + (2-p)^2 \Theta \mu^{\frac{2-2p}{2-p}}}} \right], \end{aligned}$$

where

$$g(z) = \frac{p}{2} z^{\frac{2}{p}} + z - \frac{2-p}{2} \Theta.$$

We will use Lemma 4.4 with $z = \mu^{\frac{p}{2-p}}$ to analyze the extreme value of $g(z)$ according to the value of Θ .

(I) For $0 < \Theta < \frac{2+p}{2-p}$, by Lemma 4.4 with $z = \mu^{\frac{p}{2-p}}$, a unique point

$$z_0 \in \left((1-p)\Theta, \min \left(\left(1 - \frac{p}{2}\right)\Theta, 1 \right) \right)$$

satisfies

$$\begin{cases} g(z) < 0, & 0 \leq z < z_0, \\ g(z) = 0, & z = z_0, \\ g(z) > 0, & z_0 < z \leq 1, \end{cases}$$

which implies that

$$\begin{cases} f'(\mu) > 0, & 0 \leq \mu < z_0^{\frac{2-p}{p}}, \\ f'(\mu) = 0, & \mu = z_0^{\frac{2-p}{p}}, \\ f'(\mu) > 0, & z_0^{\frac{2-p}{p}} < \mu \leq 1. \end{cases}$$

Therefore, when $\mu = z_0^{\frac{2-p}{p}}$, the function $f(\mu)$ achieves its maximal value that

$$\begin{aligned} f(z_0^{\frac{2-p}{p}}) &= \sqrt{\left(1 - (1-p)z_0^{\frac{2-p}{p}}\right)^2 + (2-p)^2\Theta \left(z_0^{\frac{2-p}{p}}\right)^{\frac{2-2p}{2-p}}} - (1-p)z_0^{\frac{2-p}{p}} \\ &= \frac{(2-p)\Theta - z_0}{z_0}. \end{aligned} \quad (4.34)$$

By (3.5), (4.34) and (4.33), there is a contradiction under the hypothesis

$$\|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\|_2 \neq 0.$$

Then

$$\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} = \mathbf{0}.$$

Due to the definition of $\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}$, we have

$$\mathbf{h} = \mathbf{0}.$$

(II) For $\Theta \geq \frac{2+p}{2-p}$, by Lemma 4.4 with $z = \mu^{\frac{p}{2-p}}$, $g(z) < 0$ for $0 \leq \mu < 1$, which means that $f'(\mu) > 0$. Therefore, when $\mu = 1$, $f(\mu)$ achieves its maximal value that

$$f_{\max}(1) = \sqrt{p^2 + (2-p)^2\Theta} - (1-p). \quad (4.35)$$

By (3.5), (4.35) and (4.33), there is a contradiction under the hypothesis

$$\|\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}\| \neq 0.$$

Then

$$\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)} = \mathbf{0}.$$

Due to the definition of $\mathbf{h}_{\max(dk)} + \mathbf{h}^{(1)}$, we have $\mathbf{h} = \mathbf{0}$. In conclusion, we complete the proof of Theorem 3.1. \square

4.3 Proof of Corollary 3.1

Proof. By $p = 1$ and (3.4),

$$\begin{aligned} \Theta = & (t - d)^{-1} \left(\omega_L + (1 - \omega_1) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right. \\ & \left. + \sum_{i=2}^L (\omega_{i-1} - \omega_i) \left(1 + \sum_{j=1}^L \rho_j - 2 \sum_{j=1}^L \alpha_j \rho_j \right)^{\frac{2-p}{2}} \right)^2. \end{aligned}$$

On one hand, the only positive solution z_0 of Eq. (3.6) with $p = 1$ is $-1 + \sqrt{1 + \Theta}$.

From $p = 1$ and $z_0 = -1 + \sqrt{1 + \Theta}$, it follows that

$$\frac{z_0}{(2 - p)\Theta - z_0} = \frac{-1 + \sqrt{1 + \Theta}}{\Theta - (-1 + \sqrt{1 + \Theta})} = \frac{1}{\sqrt{1 + \Theta}}.$$

On the other hand, for $p = 1$,

$$\frac{1}{\sqrt{p^2 + (2 - p)^2\Theta} - (1 - p)} = \frac{1}{\sqrt{1 + \Theta}}.$$

By Theorem 3.1, the condition (3.7) guarantees the exact recovery of x . □

4.4 Proof of Theorem 3.2

Proof. Theorem 3.2 can be proved by following the routine proofs of Theorem III.10 in [9] and Theorem 3.1 in this paper. We omit the details. □

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