

A Computational Algorithm to Obtain Positive Solutions for Classes of Competitive Systems

G. A. Afrouzi⁺, S. Mahdavi, Z. Naghizadeh

Department of Mathematics, Faculty of Basic Sciences, Mazandaran University, Babolsar, Iran

(Received July 31, 2006, Accepted October 5, 2006)

Abstract. Using a numerical method based on sub-super solution, we will obtain positive solution to the coupled-system of boundary value problems of the form

$-\Delta u(x) = \lambda f(x, u, v)$	$x \in \Omega$
$-\Delta v(x) = \lambda g(x, u, v)$	$x \in \Omega$
u(x) = v(x) = 0	$x \in \partial \Omega$

where f, g are C^1 functions with at least one of $f(x_{0,}, 0, 0)$ or $g(x_{0,}, 0, 0)$ being negative for some $x_0 \in \Omega$ (semipositone).

Keywords: positive solutions; sub and super-solutions **AMS Subject Classification:** 35J60, 35B30

1. Introduction

Consider positive solutions to the coupled-system of boundary value problems

$$-\Delta u(x) = \lambda f(x, u, v) \qquad x \in \Omega$$

$$-\Delta v(x) = \lambda g(x, u, v) \qquad x \in \Omega \qquad (1)$$

$$u(x) = v(x) = 0 \qquad x \in \partial \Omega$$

Where $\lambda > 0$ is a parameter, Δ is the Laplacian operator, Ω is a bounded region in \mathbb{R}^N , $N \ge 1$ with a smooth boundary $\partial \Omega$, and f, g are \mathbb{C}^1 functions with at least one of $f(x_{0,}, 0, 0)$ or $g(x_{0,}, 0, 0)$ being negative for some $x_0 \in \Omega$ (semipositone).

In this paper, we want to investigate numerically positive solution of (1) by using the method of subsuper solutions. A super solution to (1) is defined as an ordered pair of smooth functions $(\overline{u}, \overline{v})$ on Ω satisfying

$$-\Delta \overline{u}(x) \ge \lambda f(x, \overline{u}, \overline{v}) \qquad x \in \Omega$$

$$-\Delta \overline{v}(x) \ge \lambda g(x, \overline{u}, \overline{v}) \qquad x \in \Omega$$

$$\overline{u}(x) \ge 0; \overline{v}(x) \ge 0; \qquad x \in \partial \Omega.$$
 (2)

Sub solutions are similarly defined with inequalities reversed. Let $D = [\rho_1, \overline{\rho_1}] \times [\rho_2, \overline{\rho_2}]$, where

$$\underline{\rho}_1 = \inf\{\underline{u}(x) : x \in \overline{\Omega}\}, \overline{\rho}_1 = \sup\{\overline{u}(x) : x \in \overline{\Omega}\}, \underline{\rho}_2 = \inf\{\underline{v}(x) : x \in \overline{\Omega}\}, \overline{\rho}_2 = \sup\{\overline{v}(x) : x \in \overline{\Omega}\}.$$

Theorem 1. Let $(\overline{u}, \overline{v})$, $(\underline{u}, \underline{v})$ be ordered pairs of smooth functions such that $(\overline{u}, \underline{v})$ satisfies

⁺ *e-mail*: afrouzi@umz.ac.ir

$$\begin{split} &-\Delta \overline{u}(x) \geq \lambda f(x,\overline{u},\underline{v}) \qquad x \in \Omega \\ &-\Delta \underline{v}(x) \leq \lambda g(x,\overline{u},\underline{v}) \qquad x \in \Omega \\ &\overline{u}(x) \geq 0; \underline{v}(x) \leq 0; \qquad x \in \partial \Omega. \end{split}$$

And (u, \overline{v}) satisfies the corresponding reserved inequalities. Suppose that

$$\frac{\partial f}{\partial v}, \frac{\partial g}{\partial u} \le 0$$
 on $\overline{\Omega} \times D$ (cooperative system).

If $\underline{u} \leq \overline{u}$ and $\underline{v} \leq \overline{v}$ on $\overline{\Omega}$, then there is a solution (u, v) of (1) such that $\underline{u} \leq u \leq \overline{u}$ and $\underline{v} \leq v \leq \overline{v}$ on Ω .

In [1] for the first time in the literature, the authors consider a class of semipositone systems. In particular they extend many of the results discussed for the positive solutions of single equation in [2] to semipositone systems. It was shown positive solutions to (1) for either λ near the first eigenvalue λ_1 of the operator $-\Delta$ subject to Dirichlet boundary conditions, or for λ large exists. We consider following assumptions:

f,g are C^1 functions satisfying :

either
$$f(x_{0,},0,0) < 0$$
 or $g(x_{0,},0,0) < 0$ for some $x_{0} \in \Omega$ (3)
 $f(x, u, v)$

$$\lim_{u \to \infty} \frac{f(x, u, v)}{u} = 0 \quad \text{uniformly in } x, v \tag{4}$$

and

$$\lim_{v \to \infty} \frac{g(x, u, v)}{v} = 0 \quad \text{uniformly in } x, u \tag{5}.$$

To introduce additional hypotheses to prove existence results near λ_1 , first we recall the anti-maximum principal by Clement Pletier(see [4]), namely, if z_{λ} is the unique solution of

$$-\Delta z - \lambda z = -1 \qquad x \in \Omega$$

$$z = 0 \qquad x \in \partial \Omega$$
(6)

for $(\lambda_1, \lambda_1 + \delta)$, where λ_1 is the smallest eigenvalue of the problem

$$-\Delta\phi(x) = \lambda\phi(x) \qquad x \in \Omega$$

$$\phi(x) = 0 \qquad x \in \partial\Omega.$$
(7)

Let $I = [\alpha, \gamma]$ where $\alpha > \lambda_1$ and $\gamma < \lambda_1 + \delta$, and let

$$\sigma \coloneqq \max_{\lambda \in I} || z_{\lambda} |$$

Where $\|.\|$ denotes the supremum norm. Now assuming that there exists a $m_1 > 0$ such that

$$f(x,u,v) \ge u - m_1 \qquad \forall x \in \overline{\Omega}, u \in [0, m_1 \gamma \sigma], \quad v \ge 0$$
(8)

and exists a $m_2 > 0$ such that

$$g(x, u, v) \ge v - m_2 \qquad \forall x \in \overline{\Omega}, v \in [0, m_2 \gamma \sigma], \quad u \ge 0 .$$
(9)

Finally to prove existence results for λ large, in addition to (3)-(5), we assume $\exists f_1(u) \leq f(x, u, v)$ $\forall x \in \overline{\Omega}, u \geq 0, v \geq 0$ such that $f_1(r_1) = 0, f'_1(r_1) < 0,$

$$\int_{0}^{r_{1}} f_{1}(s)ds > 0 \quad \text{for some } r_{1} > 0 \tag{10}$$

And $\exists g_2(v) \le g(x, u, v)$ $\forall x \in \overline{\Omega}, u \ge 0, v \ge 0$ such that $g_2(r_2) = 0, g'_2(r_2) < 0$,

$$\int_{0}^{r_{2}} g_{2}(s) ds > 0 \quad \text{for some } r_{2} > 0$$
 (11)

2. Existence results

Theorem 2. Let $\lambda_1 \in I$ and assume (3)-(5), and (8)-(9) hold, Then (1) has a positive solution.

It was shown in [1] $(\underline{u}, \underline{v})$ is a subsolution of (1) where $\underline{u}(x) = \gamma m_1 z_{\lambda}$ and $\underline{v}(x) = \gamma m_2 z_{\lambda}$.

Now let w(x) to be the unique positive solution of

$$-\Delta w(x) = 1 \qquad x \in \Omega$$

$$w(x) \le 0 \qquad x \in \partial \Omega.$$
(12)

 $(\overline{u},\overline{v})$ is a supersolution that $\overline{u} = Jw(x)$ and $\overline{v} = \widetilde{J}w(x)$ where $J, \widetilde{J} > 0$, are sufficiently large, such that

$$\frac{1}{\lambda \|w\|} \ge \frac{f(x, J \|w\|, v)}{J \|w\|}, \frac{g(x, u, \widetilde{J} \|w\|)}{\widetilde{J} \|w\|}$$
(13)

and

$$\overline{u}(x) \ge \underline{u}(x) \text{ on } \Omega \text{ and } \overline{v}(x) \ge \underline{v}(x) \text{ on } \Omega$$
 (13)'

Theorem 3. Assume (3)-(5) and (10)-(11) hold. Then there exists a $\lambda^* > 0$ such that for every $\lambda > \lambda^*$, (1) has a positive solution.

Here we give a simple example that satisfies the hypotheses of theorem 2 and 3. Consider

$$h(x, u, v) = m\sqrt{u+1} - \frac{3m}{2} + e^{-v} \qquad \forall u \ge 0, v \ge 0$$
(14)

where m > 0 is a constant. Let

$$f(x,u,v) = h(x,u,v)$$
$$g(x,u,v) = h(x,u,v)$$

Here $f(x,0,0) = 1 - \frac{m}{2} < 0$ for m > 2, f is increasing in u, v, and $\lim_{u \to \infty} \frac{f(x, u, v)}{u} = 0$ uniformly in v. Also $g(x,0,0) = 1 - \frac{m}{2} < 0$ for m > 2, g is increasing in u, v, and $\lim_{v \to \infty} \frac{g(x, u, v)}{v} = 0$ uniformly in u. Now, to show that (8) and (9) are satisfied, it suffices to show that $h_1(u) = m\sqrt{u+1} - \frac{3m}{2}$ satisfies (8)

since $h(x, u, v) \ge h_1(u) \forall u \ge 0, v \ge 0$. Let p > 0 be such that $h_1(p) = p - m$. That is,

$$m\sqrt{p+1} - \frac{3m}{2} = p - m,$$

$$m^{2}(p+1) = \left\{p + \frac{m}{2}\right\}^{2},$$

$$p^{2} + (m - m^{2})p - \frac{3m^{2}}{4} = 0,$$

and

$$p = \frac{(m^2 - m) + \sqrt{m^4 - 2m^3 + 4m^2}}{2}$$
$$= \frac{(m^2 - m) + m\sqrt{(m - 1)^2 + 3}}{2}.$$

Hence in order that (8) be satisfied, we must have

JIC email for contribution: editor@jic.org.uk

$$\frac{m^2 - m + m\sqrt{(m-1)^2 + 3}}{2} \ge m(\sigma\alpha)$$

that is,

$$(m-1) + \sqrt{(m-1)^2 + 3} \ge 2(\sigma \alpha)$$
 (15)

Since σ and α are quantities that depend only on Ω , clearly for a given σ and α , there exists and m_0 sufficiently large such that if $m > m_0$, then (15) is satisfied and equivalently (8) will be satisfied. Thus, (9) is also satisfied for $m > m_0$.

Note that this example satisfies the hypotheses of theorem 3 also since $h(x, u, v) \ge h_1(u) \forall u \ge 0, v \ge 0$ and one can construct a function $f_1(u) \le h_1(u)$ satisfying (10).

3. Numerical Results

We see in section 2 that there must always exists a solution for problems such as (1) between a subsolution $(\underline{u}, \underline{v})$ and a super-solution $(\overline{u}, \overline{v})$ when $\frac{\partial f}{\partial v}, \frac{\partial g}{\partial u} \leq 0$

Consider the coupled-system boundary value problems

$$-\Delta u(x) = \lambda f(x, u, v) \qquad x \in \Omega$$

$$-\Delta v(x) = \lambda g(x, u, v) \qquad x \in \Omega$$

$$u(x) = v(x) = 0 \qquad x \in \partial \Omega$$
(16)

Since f, g are C^1 functions, there exists positive constants k_1, k_2 such that $\frac{\partial f}{\partial u} \ge -k_1$, and $\frac{\partial g}{\partial v} \ge -k_2$ on $\overline{O} = 0$. There exists a static structure of the second state of t

 $\overline{\Omega} \times D$. Thus we can study the equivalent system

$$-\Delta u(x) + \lambda k_1 u(x) = \lambda f(x, u, v) + \lambda k_1 u(x) = \lambda f(x, u, v) \quad x \in \Omega$$

$$-\Delta v(x) + \lambda k_2 v(x) = \lambda g(x, u, v) + \lambda k_2 v(x) = \lambda \hat{g}(x, u, v) \quad x \in \Omega$$

$$u(x) = v(x) = 0 \qquad x \in \partial \Omega$$
 (17)

u(x) = v(x) = 0apping $T: (u, v_1) \rightarrow (u, v_2) = T(u, v_1)$

The mapping
$$T: (u_1, v_1) \to (u_2, v_2), \ (u_2, v_2) = T(u_1, v_1)$$

$$(u_1, v_1) \in [\underline{u}, \overline{u}] \times [\underline{v}, \overline{v}] \quad \forall x \in \Omega$$

Where (u_2, v_2) is the unique solution of the coupled-system

$$-\Delta u_{2}(x) + \lambda k_{1}u_{2}(x) = \lambda f(x, u_{1}, v_{1}) + \lambda k_{1}u_{1}(x) \qquad x \in \Omega$$

$$-\Delta v_{2}(x) + \lambda k_{2}v_{2}(x) = \lambda g(x, u_{1}, v_{1}) + \lambda k_{2}v_{1}(x) \qquad x \in \Omega$$

$$u_{2}(x) = v_{2}(x) = 0 \qquad x \in \partial\Omega$$
(18)

satisfied the hypotheses of Schauder fixed point theorem, and then we can conclude that

 $\exists (u, v) \in D \qquad \qquad T(u, v) = (u, v)$

so (u, v) is a solution of (1) (see [3]).

By letting $\hat{f}(x, u, v) = \lambda f(x, u, v) + \lambda k_1 u(x)$ and $\hat{g}(x, u, v) = \lambda g(x, u, v) + \lambda k_2 v(x)$, we use the following iteration to obtain solution:

$$u_{0}(x) = \underline{u}, v_{0}(x) = \overline{v} \qquad n = 0,1,2,...$$

$$(\Delta - \lambda k_{1})u_{n+1} = -\hat{f}(x,u_{n},v_{n}) \qquad x \in \Omega$$

$$(\Delta - \lambda k_{2})v_{n+1} = -\hat{g}(x,u_{n+1},v_{n}) \qquad x \in \Omega$$

$$u_{n+1} = 0 = v_{n+1} \qquad x \in \partial\Omega.$$
(19)

We can also use $u_0(x) = \overline{u}, v_0(x) = \underline{v}$ as initial guesses. we use following algorithm

sub- and super-solution algorithm

- 1. Find $u_0(x) = \underline{u}, v_0(x) = \overline{v}$. Choose numbers $k_1, k_2 > 0$;
- 2. Solve the boundary value system (19);
- 3. If $||u_{n+1} u_n|| < \varepsilon$ and $||v_{n+1} v_n|| < \varepsilon$, output and stop. Else go to step 2.

Now we want to apply the algorithm for:

$$-\Delta u(x) = \lambda (m\sqrt{u+1} - \frac{3m}{2} + e^{-v})$$

$$-\Delta v(x) = \lambda (m\sqrt{v+1} - \frac{3m}{2} + e^{-u}) \qquad x \in \Omega$$

$$u(x) = v(x) = 0 \qquad x \in \partial\Omega$$
(20)

For doing step 1, we solve the problem

$$-\Delta z - \lambda z = -1 \qquad x \in \Omega$$

$$z = 0 \qquad x \in \partial \Omega$$
(21)

to obtain \underline{u} . We know from section 2 that problem (21) has a positive solution for $(\lambda_1, \lambda_1 + \delta)$. The obtained results show there is an array of positive solution for $\lambda \in (17,35)$ so λ_1 is around 17.

For brevity we express just some of those numerical results:

x / y	0.2	0.4	0.6	0.8
0.2	-0.268	0.423	-0.431	-0.283
0.4	-0.447	-0.701	-0.718	-0.493
0.6	-0.513	-0.753	-0.778	-0.636
0.8	-0.505	-0.528	-0.497	-0.345

Approximation of z_{λ} for $\lambda = 15$

Approximation of z_{λ} for $\lambda = 17$

x / y	0.2	0.4	0.6	0.8
0.2	1.895	3.067	3.130	2.022
0.4	3.266	5.199	5.341	3.625
0.6	3.789	5.626	5.818	4.172
0.8	3.727	3.912	3.676	2.514

Approximation of z_{λ} for $\lambda = 30$

x / y	0.2	0.4	0.6	0.8
0.2	0.002	0.017	0.021	0.008
0.4	0.028	0.062	0.068	0.041
0.6	0.050	0.087	0.093	0.070
0.8	0.054	0.060	0.056	0.033

Approximation of z_{λ} for $\lambda = 36$

x / y	0.2	0.4	0.6	0.8
0.2	-0.001	0.012	0.016	0.005
0.4	0.024	0.056	0.063	0.038

JIC email for contribution: editor@jic.org.uk

0.6	0.048	0.084	0.091	0.068
0.8	0.053	0.060	0.056	0.033

Let $\underline{u} = \gamma m_{1, z_{\lambda}}(x)$ where γ and m obtained from section 1, 2 and to obtain $\overline{\nu}$ for $\lambda \in I$ ($I = [\alpha, \gamma]$ where $\alpha > \lambda_1$ and $\gamma < \lambda_1 + \delta$) we solve

$$-\Delta v(x) = 1 \qquad x \in \Omega$$

$$v(x) = 0 \qquad x \in \partial \Omega$$
(22)

by finite difference (see [5,6]). We choose J such that (13), (13) ' are satisfied.

We execute algorithm for $\lambda \in [17.1, 34.9]$. It is easy to see that u = v for problem (20).

For brevity we express just some of those numerical results:

<i>x / y</i>	0.2	0.4	0.6	0.8
0.2	1.009×10^{4}	1.510×10^{4}	1.510×10^{4}	1.009×10^{4}
0.4	1.510×10^{4}	2.777×10^{4}	2.777×10^{4}	1.510×10^{4}
0.6	1.510×10^{4}	2.777×10^{4}	2.777×10^{4}	1.510×10^{4}
0.8	1.009×10^{4}	1.510×10^{4}	1.510×10^{4}	1.009×10^{4}

Approximation of *u* for $\lambda = 17.1$

Approx	imation of	<i>u</i> for	$\lambda = 25$	
				_

<i>x / y</i>	0.2	0.4	0.6	0.8
0.2	2.173×10^{4}	3.253×10^{4}	3.253×10^{4}	2.173×10^{4}
0.4	3.253×10^{4}	4.902×10^{4}	4.902×10^{4}	3.253×10^{4}
0.6	3.253×10^{4}	4.902×10^{4}	4.902×10^{4}	3.253×10^{4}
0.8	2.173×10^{4}	3.253×10^{4}	3.253×10^{4}	2.173×10^{4}

Approximation of *u* for $\lambda = 30$

<i>x</i> / <i>y</i>	0.2	0.4	0.6	0.8
0.2	3.139×10^{4}	4.697×10^{4}	4.697×10^{4}	3.139×10^{4}
0.4	4.697×10^{4}	7.078×10^{4}	7.078×10^{4}	4.697×10^{4}
0.6	4.697×10^{4}	7.078×10^{4}	7.078×10^{4}	4.697×10^{4}
0.8	3.139×10^{4}	4.697×10^{4}	4.697×10^{4}	3.139×10^{4}

Approximation of u for $\lambda = 34.9$

x/y	0.2	0.4	0.6	0.8
0.2	4.256×10^{4}	6.368×10^4	6.368×10^4	4.256×10^{4}
0.4	6.368×10^4	9.596×10^{4}	9.596×10^{4}	6.368×10^4
0.6	6.368×10^4	9.596×10^{4}	9.596×10^{4}	6.368×10^4
0.8	4.256×10^{4}	6.368×10^4	6.368×10^4	4.256×10^{4}

Our numerical results (in following tables) show that there exist $\lambda^* > 0$ such that for every $\lambda > \lambda^*$, (20) has a positive solution. In this case $\lambda^* = 166.696$ with decimal accuracy.

Approximation of *u* for $\lambda = 170$

x/y	0.2	0.4	0.6	0.8
0.2	1.019×10^{6}	1.524×10^{6}	1.524×10^{6}	1.019×10^{6}
0.4	1.524×10^{6}	2.297×10^{6}	2.297×10^{6}	1.524×10^{6}
0.6	1.524×10^{6}	2.297×10^{6}	2.297×10^{6}	1.524×10^{6}
0.8	1.019×10^{6}	1.524×10^{6}	1.524×10^{6}	1.019×10^{6}

x / y	0.2	0.4	0.6	0.8
0.2	0.883×10^{7}	1.321×10^{7}	1.321×10^{7}	0.883×10^{7}
0.4	1.321×10^{7}	1.990×10^{7}	1.990×10^{7}	1.321×10^{7}
0.6	1.321×10^{7}	1.990×10^{7}	1.990×10^{7}	1.321×10^{7}
0.8	0.883×10^{7}	1.321×10^{7}	1.321×10^{7}	0.883×10^{7}

Approximation of *u* for $\lambda = 500$

x / y	0.2	0.4	0.6	0.8
0.2	3.534×10^{7}	5.286×10^{7}	5.286×10^{7}	3.534×10^{7}
0.4	5.286×10^{7}	7.963×10^{7}	7.963×10^{7}	5.286×10^{7}
0.6	5.286×10^{7}	7.963×10^{7}	7.963×10^{7}	5.286×10^{7}
0.8	3.534×10^{7}	5.286×10^{7}	5.286×10^{7}	3.534×10^{7}

Approximation of *u* for $\lambda = 1000$

4. References

- [1] V. Anuradha, A. Castro and R. Shivaji. Existence Results for Semipositone Systems. Dynamic Systems and Applications. **5**:219-228.
- [2] V. Anuradha, S. Dikens and R. Shivaji. Existence Results for Non-autonomous el lip Boundary Value Problems. Electronic Journal of Diff. Eqns, 4:1-10.
- [3] A. Canada and J. L. Gamez. Elliptic Systems with Nonlinear Diusion in Population dynamics, Differential Equations and Dynamical Systems, 3 (1995) 189-204.
- [4] P. Clement and L. A. Peletier. An anti-maximum principle for second order elliptic operators, Di.erential Equations 34 (1979) 218-229.
- [5] M. Dehghan. Numerical procedures for a boundary value problem with a non-linear boundary condition, Applied mathematics and computation 147 (2004) 291-306.
- [6] I. G. Petrovsky. Lectures on partial di.erential equations, Dover publications, Inc. (1991).