# THE OPTIMAL PRECONDITIONING IN THE DOMAIN DECOMPOSITION METHOD FOR WILSON ELEMENT* 

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#### Abstract

This paper discusses the optimal preconditioning in the domain decomposition method for Wilson element. The process of the preconditioning is composed of the resolution of a small scale global problem based on a coarser grid and a number of independent local subproblems, which can be chosen arbitrarily. The condition number of the preconditioned system is estimated by some characteristic numbers related to global and local subproblems. With a proper selection, the optimal preconditioner can be obtained, while the condition number is independent of the scale of the problem and the number of subproblems.


## 1. The Construction of Preconditioner

Let $\Omega$ be a polygon domain in $R^{2}, f \in L^{2}(\Omega)$. Consider the homogeneous Dirichlet boundary value problem of Poisson equation,

$$
\left\{\begin{array}{l}
-\triangle u=f, \quad \text { in } \Omega  \tag{1.1}\\
\left.u\right|_{\partial \Omega}=0
\end{array}\right.
$$

Assume that, for domain $\Omega$, there are a coarser subdivision $\mathrm{T}_{H}$ with mesh size $H$ and an another one $\mathrm{T}_{h}$ with mesh size $h$, which is obtained by refining $\mathrm{T}_{H}$. The both subdivisions satisfy the quasi-uniformity and the inverse hypothesis.

For a given element $T, P_{m}(T)$ denotes the space of all polynomials with the degree not greater than $m, Q_{m}(T)$ denotes the space of all polynomials with the degree corresponding to $x$ or $y$ not greater than $m$.

Let $V_{H}$ and $V_{h}$ be some nonconforming finite element spaces corresponding to $\mathrm{T}_{H}$ and $\mathrm{T}_{h}$ respectively. For problem (1.1), the nodal parameters on the boundary $\partial \Omega$ are all zero. For finite element spaces $V_{h}$ and $V_{H}$, the finite element equations for problem (1.1) are

$$
\begin{equation*}
a_{h}\left(u_{h}, v_{h}\right)=\left(f, v_{h}\right), \quad \forall v_{h} \in V_{h} \tag{1.2}
\end{equation*}
$$

[^0]\[

$$
\begin{equation*}
a_{H}\left(u^{H}, v^{H}\right)=\left(f, v^{H}\right), \quad \forall v^{H} \in V_{H}, \tag{1.3}
\end{equation*}
$$

\]

respectively. Where $(\cdot, \cdot)$ is $L^{2}(\Omega)$ inner product and

$$
\begin{aligned}
& a_{h}(v, w)=\sum_{T \in \mathbf{T}_{h}} \int_{T}\left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial x}+\frac{\partial u}{\partial y} \frac{\partial v}{\partial y}\right) d x d y \\
& a_{H}(v, w)=\sum_{T \in \mathbf{T}_{H}} \int_{T}\left(\frac{\partial u}{\partial x} \frac{\partial v}{\partial x}+\frac{\partial u}{\partial y} \frac{\partial v}{\partial y}\right) d x d y
\end{aligned}
$$

For $v \in V_{h}$, denote the vector of its nodal parameters by $C_{h}(v)$, and for $v \in V_{H}$, denote the vector of its nodal parameters by $C_{H}(v)$. Thus, equations (1.2) and (1.3) can be written as

$$
\begin{align*}
& A_{h} C_{h}\left(u_{h}\right)=F_{h}  \tag{1.4}\\
& A_{H} C_{H}\left(u^{H}\right)=F_{H} \tag{1.5}
\end{align*}
$$

where $A_{h}, A_{H}$ are the stiffness matrices corresponding to problems (1.2) and (1.3) respectively, and $F_{h}, F_{H}$ are the loading vectors.

Now consider how to solve (1.2). The Preconditioned Conjugate Gradient method (PCG) would be used. So the preconditioning matrix $Q$ needs to be constructed.

Let $\left\{\omega_{1}, \omega_{2}, \cdots, \omega_{M}\right\}$ be a domain decomposition of $\Omega$, i.e., $\bar{\Omega}=\cup_{k=1}^{M} \overline{\omega_{k}}$, and $\omega_{m} \cap$ $\omega_{n}=\emptyset(m \neq n)$. For each $\omega_{k}$, it is extended to $\Omega_{k}$, such that the boundary of $\Omega_{k}$ is consists of the edges of $\mathrm{T}_{h}$ and

$$
\begin{equation*}
\operatorname{dist}\left\{\partial \omega_{k}, \partial \Omega_{k}\right\} \geq L \tag{1.6}
\end{equation*}
$$

where $L$ is a fixed positive constant. For each element $T \in \mathrm{~T}_{h}$, the number of subdomains $\bar{\Omega}_{k}$ containing $T$ does not exceed a fixed number.

Corresponding to $\mathrm{T}_{h}$, a subdivision of $\Omega_{k}$ can be obtained, and the corresponding nonforming finite element space is denoted by $V_{h, k}$. The corresponding finite element equation is

$$
\begin{equation*}
a_{k}\left(u_{k}, v_{k}\right)=\left(f, v_{k}\right)_{k}, \quad \forall v_{k} \in V_{h, k}, \tag{1.7}
\end{equation*}
$$

where $(\cdot, \cdot)_{k}$ is $L^{2}\left(\Omega_{k}\right)$ inner product and

$$
a_{k}\left(u_{k}, v_{k}\right)=\sum_{T \in \mathbf{T}_{h}, T \subset \bar{\Omega}_{k}} \int_{T}\left(\frac{\partial u_{k}}{\partial x} \frac{\partial v_{k}}{\partial x}+\frac{\partial u_{k}}{\partial y} \frac{\partial v_{k}}{\partial y}\right) d x d y .
$$

The stiffness matrix is denoted by $A_{k}$.
Let $E_{k}$ be the zero extension operator from $V_{h, k}$ to $V_{h}$, i.e., $\forall v_{k} \in V_{h, k}, \forall T \in \mathrm{~T}_{h}$

$$
\left.E_{k} v_{k}\right|_{T}= \begin{cases}\left.v_{k}\right|_{T}, & T \subset \bar{\Omega}_{k}  \tag{1.8}\\ 0, & \text { otherwise }\end{cases}
$$

For $v_{k} \in V_{h, k}$, its nodal parameter vector is denoted by $C_{k}\left(v_{k}\right)$. In the sense of nodal parameter vectors, a mapping matrix $\mathbf{E}_{k}$ is given, that is

$$
\begin{equation*}
C_{h}\left(E_{k} v_{k}\right)=\mathbf{E}_{k} C_{k}\left(v_{k}\right), \quad \forall v_{k} \in V_{h, k} . \tag{1.9}
\end{equation*}
$$

Let $I_{H}$ be a linear operator from $V_{H}$ to $V_{h}$. Let $\mathbf{I}_{H}$ be the matrix such that

$$
\begin{equation*}
C_{h}\left(I_{H} v^{H}\right)=\mathbf{I}_{H} C_{H}\left(v^{H}\right), \quad \forall v^{H} \in V_{H} . \tag{1.10}
\end{equation*}
$$

The expression for the inverse $Q^{-1}$ of the preconditioner $Q$ is defined as follows,

$$
\begin{equation*}
Q^{-1}=\mathbf{I}_{H} A_{H}^{-1} \mathbf{I}_{H}^{\top}+\sum_{k=1}^{M} \mathbf{E}_{k} A_{k}^{-1} \mathbf{E}_{k}^{\top}, \tag{1.11}
\end{equation*}
$$

while $Q^{-1}$ is symmetric and positive.
In the PCG iteration, only $Q^{-1}$ not $Q$ will take part in the operation, the expression for $Q$ is not necessary. The process of $Q^{-1}$ is to solve the finite element equations on coarser subdivision and the subdomains simultaneously. The computing is fully parallel.

The convergence of PCG method is dependent on the condition number of matrix $Q^{-1} A_{h}$. Smaller the condition number is, faster the convergence is. The condition number of $Q^{-1} A_{h}$ is bounded by the ratio of the upper bounds of the generalized Rayleich quotient

$$
\begin{equation*}
R(v)=\frac{\left(A_{h} Q^{-1} A_{h} C_{h}(v), C_{h}(v)\right)}{\left(A_{h} C_{h}(v), C_{h}(v)\right)}, \quad \forall v \in V_{h} . \tag{1.12}
\end{equation*}
$$

to the low one.
The remainder of the paper will give the linear operator $I_{H}$ for Wilson element, and estimate $R(v)$ and get the bound of the condition number.

Throughout the paper, $C$ always denotes the positive constant independent of $H$, $h$ and the choice of the subdomains.

For a set $G \in R^{2}$ and an integer $m$, Sobolev semi-norm is denoted by $|\cdot|_{m, G}$. For subdivisions $\mathrm{T}_{H}$ and $\mathrm{T}_{h}$, define the following discrete Sobolev norms,

$$
|\cdot|_{m, H}=\left(\sum_{T \in \mathbf{T}_{H}}|\cdot|_{m, T}^{2}\right)^{1 / 2}, \quad|\cdot|_{m, h}=\left(\sum_{T \in \mathbf{T}_{h}}|\cdot|_{m, T}^{2}\right)^{1 / 2} .
$$

## 2. Wilson Element

In the case of Wilson element, the subdivision elements are rectangles. Wilson finite element space $V_{h}=\left\{v\left|v \in L^{2}(\Omega), v\right|_{T} \in P_{2}(T), \forall T \in \mathrm{~T}_{h}\right.$, and $v$ is continuous at vertices of $\mathrm{T}_{h}$ and $v$ vanishes at the vertices on $\left.\partial \Omega\right\}$. Similarly, spaces $V_{H}$ and $V_{h, k}$ can be defined. The function $v$ of Wilson space is uniquely determined by its values at the vertices, and the values of $\frac{\partial^{2}}{\partial x^{2}} v$ and $\frac{\partial^{2}}{\partial y^{2}} v$ on all elements.

The bilinear interpolation operator using the function values at the vertices, for element $T$, is denoted by $Q_{T}^{1} . Q_{H}^{1}$ and $Q_{h}^{1}$ are the interpolation operators corresponding to $\mathrm{T}_{H}$ and $\mathrm{T}_{h}$ respectively.

For all $v^{H} \in V_{H}$, define $I_{H} v^{H} \in V_{h}$ as follows,

1. $I_{H} v^{H}$ equals to $Q_{H}^{1} v^{H}$ at the vertices of $\mathrm{T}_{h}$.
2. For each element $T^{\prime}$ of $\mathrm{T}_{h}$, there exists an element $T \in \mathrm{~T}_{H}$ with $T^{\prime} \subset T$, then

$$
\left.\frac{\partial^{2}}{\partial x^{2}} I_{H} v^{H}\right|_{T^{\prime}}=\left.\frac{H}{h} \frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T},\left.\quad \frac{\partial^{2}}{\partial y^{2}} I_{H} v^{H}\right|_{T^{\prime}}=\left.\frac{H}{h} \frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}
$$

Before estimating the condition number of $Q^{-1} A_{h}$, some preparation results will be given.

Lemma 1. There exists a constant $C$ independent of $H, h$, such that,

$$
\begin{equation*}
\left|v^{H}-I_{H} v^{H}\right|_{m, h} \leq C H^{1-m}\left|v^{H}\right|_{1, H}, \quad m=0,1 \forall v^{H} \in V_{H} \tag{2.1}
\end{equation*}
$$

Proof. For a given rectangle $T$, its four vertices are denoted by $A_{T}^{i}(1 \leq i \leq 4)$. It is easy to show that for arbitrary element $T$ in $\mathrm{T}_{H}$ or in $\mathrm{T}_{h}$,

$$
\begin{gather*}
\frac{1}{C}|p|_{0, T}^{2} \leq\left\{\sum_{i=1}^{4}|T|\left|p\left(A_{T}^{i}\right)\right|^{2}+|T|^{3}\left(\left|\frac{\partial^{2} p}{\partial x^{2}}\right|^{2}+\left|\frac{\partial^{2} p}{\partial y^{2}}\right|^{2}\right)\right\} \leq C|p|_{0, T}^{2}  \tag{2.2}\\
\frac{1}{C}|p|_{1, T}^{2} \leq\left\{\sum_{1 \leq i, j \leq 4}\left|p\left(A_{T}^{i}\right)-p\left(A_{T}^{j}\right)\right|^{2}+|T|^{2}\left(\left|\frac{\partial^{2} p}{\partial x^{2}}\right|^{2}+\left|\frac{\partial^{2} p}{\partial y^{2}}\right|^{2}\right)\right\} \leq C|p|_{1, T}^{2} \tag{2.3}
\end{gather*}
$$

are true for all $p \in P_{2}(T)$, where $|T|$ is the area of $T$.
Now let $v^{H} \in V_{H}$ and $T \in \mathrm{~T}_{H}$, then from the definition of $I_{H}$ and (2.2),

$$
\begin{aligned}
\left|v^{H}-I_{H} v^{H}\right|_{0, T}^{2}= & \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left|v^{H}-I_{H} v^{H}\right|_{0, S}^{2} \leq C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{i=1}^{4} h^{2}\left|\left(v^{H}-I_{H} v^{H}\right)\left(A_{S}^{i}\right)\right|^{2}\right. \\
& \left.+h^{6}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}}\left(v^{H}-I_{H} v^{H}\right)\right|_{S}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}}\left(v^{H}-I_{H} v^{H}\right)\right|_{S}\right|^{2}\right)\right\} \\
= & C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{i=1}^{4} h^{2}\left|\left(Q_{h}^{1}-Q_{H}^{1}\right) v^{H}\left(A_{S}^{i}\right)\right|^{2}\right. \\
& \left.+h^{6}\left(1-\frac{H}{h}\right)^{2}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
\leq & C \sum_{S \in \mathbf{T}_{h}, S \subset T}\left\{\left|\left(Q_{h}^{1}-Q_{H}^{1}\right) v^{H}\right|_{0, S}^{2}+H^{2} h^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right| T\right|^{2}\right)\right\}
\end{aligned}
$$

By the interpolation property and the inverse inequality, one gets

$$
\left|v^{H}-I_{H} v^{H}\right|_{0, T}^{2} \leq C H^{2}\left|v^{h}\right|_{1, T}^{2}\left\{1+\sum_{S \in \mathrm{~T}_{h}, S \subset T} h^{4} H^{-4}\right\}
$$

Since the number of the elements contained in $T$ is bounded by $\mathrm{CH}^{2} / h^{2}$, one has

$$
\begin{equation*}
\left|v^{H}-I_{H} v^{H}\right|_{0, T}^{2} \leq C H^{2}\left|v^{h}\right|_{1, T}^{2} \tag{2.4}
\end{equation*}
$$

From the definition of $I_{H}$ and (2.3),

$$
\begin{aligned}
\sum_{S \in \mathrm{~T}_{h}, S \subset T} \mid v^{H}- & \left.I_{H} v^{H}\right|_{1, S} ^{2} \leq C \\
& \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{1 \leq i, j \leq 4}\left|\left(v^{H}-I_{H} v^{H}\right)\left(A_{S}^{i}\right)-\left(v^{H}-I_{H} v^{H}\right)\left(A_{S}^{j}\right)\right|^{2}\right. \\
= & \left.C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{1 \leq i, j \leq 4}\left|\left(Q_{h}^{1}-Q_{H}^{1}\right) v^{H}\left(A_{S}^{i}\right)-\left(Q_{h}^{1}-Q_{H}^{1}\right)\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}}\left(v^{H}-I_{H} v^{H}\right)\right|_{S}^{j}\right|^{2}\right)\right\} \\
& \left.+h^{4}\left(1-\frac{H}{h}\right)^{2}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right| T\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
\leq & C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\left|\left(Q_{h}^{1}-Q_{H}^{1}\right) v^{H}\right|_{1, S}^{2}+H^{2} h^{2}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\}
\end{aligned}
$$

It leads to

$$
\begin{equation*}
\sum_{S \in \mathrm{~T}_{h}, S \subset T}\left|v^{H}-I_{H} v^{H}\right|_{1, S}^{2} \leq C\left|v^{H}\right|_{1, T}^{2} \tag{2.5}
\end{equation*}
$$

Lemma 1 follows from (2.4) and (2.5).
Lemma 2. There exists a constant $C$ independent of $H, h$, such that,

$$
\begin{equation*}
\left|v^{H}\right|_{1, H} \leq C\left|I_{H} v^{H}\right|_{1, h}, \quad \forall v^{H} \in V_{H} \tag{2.6}
\end{equation*}
$$

Proof. Let $v^{H} \in V_{h}$ and $T \in \mathrm{~T}_{H}$. (2.3) gives

$$
\begin{aligned}
\left|v^{H}\right|_{1, T}^{2} \leq & C\left\{\sum_{1 \leq i, j \leq 4}\left|v^{H}\left(A_{T}^{i}\right)-v^{H}\left(A_{T}^{j}\right)\right|^{2}+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right| T\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
= & C\left\{\sum_{1 \leq i, j \leq 4}\left|Q_{H}^{1} v^{H}\left(A_{T}^{i}\right)-Q_{H}^{1} v^{H}\left(A_{T}^{j}\right)\right|^{2}+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
\leq & C\left\{\left|Q_{H}^{1} v^{H}\right|_{1, T}^{2}+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right| T\right|^{2}\right)\right\} \\
= & C\left\{\sum_{S \in \mathbf{T}_{h}, S \subset T}\left|Q_{H}^{1} v^{H}\right|_{1, S}^{2}+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
\leq & C\left\{\sum_{S \in \mathrm{~T}_{h}, S \subset T} \sum_{1 \leq i, j \leq 4}\left|Q_{H}^{1} v^{H}\left(A_{S}^{i}\right)-Q_{H}^{1} v^{H}\left(A_{S}^{j}\right)\right|^{2}\right. \\
& \left.+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right| T\right|^{2}\right)\right\}
\end{aligned}
$$

$$
\begin{aligned}
= & C\left\{\sum_{S \in \mathbf{T}_{h}, S \subset T} \sum_{1 \leq i, j \leq 4}\left|I_{H} v^{H}\left(A_{S}^{i}\right)-I_{H} v^{H}\left(A_{S}^{j}\right)\right|^{2}\right. \\
& \left.+H^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\}
\end{aligned}
$$

Noticing that $H^{2} / h^{2}$ is not greater than the number of elements in $\mathrm{T}_{h}$ which are contained in $T$, one gets, from the definition of $I_{H}$,

$$
\begin{aligned}
\left|v^{H}\right|_{1, T}^{2} \leq & C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{1 \leq i, j \leq 4}\left|I_{H} v^{H}\left(A_{S}^{i}\right)-I_{H} v^{H}\left(A_{S}^{j}\right)\right|^{2}\right. \\
& \left.+H^{2} h^{2}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} v^{H}\right|_{T}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} v^{H}\right|_{T}\right|^{2}\right)\right\} \\
\leq & C \sum_{S \in \mathrm{~T}_{h}, S \subset T}\left\{\sum_{1 \leq i, j \leq 4}\left|I_{H} v^{H}\left(A_{S}^{i}\right)-I_{H} v^{H}\left(A_{S}^{j}\right)\right|^{2}\right. \\
& \left.+h^{4}\left(\left.\left|\frac{\partial^{2}}{\partial x^{2}} I_{H} v^{H}\right|_{S}\right|^{2}+\left.\left|\frac{\partial^{2}}{\partial y^{2}} I_{H} v^{H}\right| S\right|^{2}\right)\right\}
\end{aligned}
$$

Combining (2.3) and the above inequality, one has

$$
\begin{equation*}
\left|v^{H}\right|_{1, T}^{2} \leq C \sum_{S \in \mathbf{T}_{h}, S \subset T}\left|I_{H} v^{H}\right|_{1, S}^{2} . \tag{2.7}
\end{equation*}
$$

Lemma 2 follows.
Let $P: L^{2}(\Omega) \rightarrow V_{H}$ is the orthogonal projection operator in the sense of $L^{2}(\Omega)$, that is, for $v \in L^{2}(\Omega), P v \in V_{H}$ and

$$
\left(v, v^{H}\right)=\left(P v, v^{H}\right), \quad \forall v^{H} \in V_{H}
$$

Lemma 3. For all $v \in H_{0}^{1}(\Omega)$, the following estimates are uniformly true,

$$
\begin{gather*}
|v-P v|_{m, H} \leq C H^{1-m}|v|_{1, H}, \quad m=0,1,  \tag{2.8}\\
|P v|_{1, H} \leq C|v|_{1, H} \tag{2.9}
\end{gather*}
$$

Lemma 3 can be proved by the similar way used in [2].

## 3. The Condition Number

Let $P_{H}: V_{h} \rightarrow I_{H} V_{H}$ and $P_{k}: V_{h} \rightarrow E_{k} V_{h, k}(k=1,2, \cdots, M)$ be the orthogonal projection operators in the sense of inner product $a_{h}(\cdot, \cdot)$, that is, for $v_{h} \in V_{h}, P_{H} v_{h} \in$ $I_{H} V_{H}$ and

$$
\begin{equation*}
a_{h}\left(P_{H} v_{h}, I_{H} v^{H}\right)=a_{h}\left(v_{h}, I_{H} v^{H}\right), \quad \forall v^{H} \in V_{H} \tag{3.1}
\end{equation*}
$$

and $P_{k} v_{h} \in E_{k} V_{h, k}$ and

$$
\begin{equation*}
a_{h}\left(P_{k} v_{h}, E_{k} v_{k}\right)=a_{h}\left(v_{h}, E_{k} v_{k}\right), \quad \forall v_{k} \in V_{h, k} . \tag{3.2}
\end{equation*}
$$

For all $v \in V_{h}$, let $u_{v}^{H} \in V_{H}$ be the solution of equation

$$
\begin{equation*}
a_{H}\left(u_{v}^{H}, v^{H}\right)=a_{h}\left(v, I_{H} v^{H}\right), \quad \forall v^{H} \in V_{H}, \tag{3.3}
\end{equation*}
$$

that is,

$$
A_{H} C_{H}\left(u_{v}^{H}\right)=\mathbf{I}_{H}^{\top} A_{h} C_{h}(v) .
$$

It is easy to show that

$$
\begin{equation*}
\left(A_{h} Q^{-1} A_{h} C_{h}(v), C_{h}(v)\right)=a_{h}\left(u_{v}^{H}, u_{v}^{H}\right)+\sum_{k=1}^{M} a_{h}\left(P_{k} v, v\right), \quad \forall v \in V_{h} . \tag{3.4}
\end{equation*}
$$

Lemma 4. There exists a constant $C$ independent of $H, h$ and the choice of subdomains, such that,

$$
\begin{equation*}
R(v) \leq C, \quad \forall v \in V_{h} \tag{3.5}
\end{equation*}
$$

Proof. By the way used in Lemma 2.1 in paper [4], one can prove that

$$
\begin{equation*}
\sum_{k=1}^{M} a_{h}\left(P_{k} v, v\right) \leq C a_{h}(v, v), \quad \forall v \in V_{h} . \tag{3.6}
\end{equation*}
$$

From (3.3) and (2.1), one gets

$$
\begin{align*}
a_{H}\left(u_{v}^{H}, u_{v}^{H}\right) & =a_{h}\left(v, I_{H} u_{v}^{H}\right) \leq a_{h}(v, v)^{1 / 2} a_{h}\left(I_{H} u_{v}^{H}, I_{H} u_{v}^{H}\right)^{1 / 2} \leq C a_{h}(v, v)^{1 / 2}\left|I_{H} u_{v}^{H}\right|_{1, h} \\
& \leq C a_{h}(v, v)^{1 / 2}\left|u_{v}^{H}\right|_{1, H} \leq C a_{h}(v, v)^{1 / 2} a_{H}\left(u_{v}^{H}, u_{v}^{H}\right)^{1 / 2} \\
a_{H}\left(u_{v}^{H}, u_{v}^{H}\right) & \leq C a_{h}(v, v) . \tag{3.7}
\end{align*}
$$

Lemma 4 follows from (3.6) and (3.7).
Lemma 5. For all $v \in V_{h}$,

$$
\begin{equation*}
a_{h}\left(P_{H} v, v\right)+\sum_{k=1}^{M} a_{h}\left(P_{k} v, v\right) \leq C a_{H}\left(u_{v}^{H}, u_{v}^{H}\right)+\sum_{k=1}^{M} a_{h}\left(P_{k} v, v\right) . \tag{3.8}
\end{equation*}
$$

Proof. It is sufficient to show the following inequality

$$
\begin{equation*}
a_{h}\left(P_{H} v, v\right) \leq C a_{H}\left(u_{v}^{H}, u_{v}^{H}\right) . \tag{3.9}
\end{equation*}
$$

By (3.1) and (3.3),

$$
a_{h}\left(P_{H} v, I_{H} v^{H}\right)=a_{h}\left(v, I_{H} v^{H}\right)=a_{H}\left(u_{v}^{H}, v^{H}\right), \quad \forall v^{H} \in V_{H},
$$

and

$$
\begin{aligned}
a_{h}\left(P_{H} v, P_{H} v\right)^{1 / 2} & =\sup _{0 \neq w \in V_{H}} \frac{a_{h}\left(P_{H} v, I_{H} w\right)}{a_{h}\left(I_{H} w, I_{H} w\right)^{1 / 2}}=\sup _{0 \neq w \in V_{H}} \frac{a_{H}\left(u_{v}^{H}, w\right)}{a_{h}\left(I_{H} w, I_{H} w\right)^{1 / 2}} \\
& \leq a_{H}\left(u_{v}^{H}, u_{v}^{H}\right)^{1 / 2} \sup _{0 \neq w \in V_{H}} \frac{a_{H}(w, w)^{1 / 2}}{a_{h}\left(I_{H} w, I_{H} w\right)^{1 / 2}} \\
& \leq C a_{H}\left(u_{v}^{H}, u_{v}^{H}\right)^{1 / 2} \sup _{0 \neq w \in V_{H}} \frac{|w|_{1, H}}{\left|I_{H} w\right|_{1, h}},
\end{aligned}
$$

(2.6) leads to (3.9).

Lemma 6. For all $v \in V_{h}$,

$$
\begin{equation*}
a_{h}(v, v) \leq C\left(1+\frac{H^{2}}{L^{2}}\right)\left(1+\frac{h^{2}}{L^{2}}\right)\left[a_{h}\left(P_{H} v, v\right)+\sum_{k=1}^{M} a_{h}\left(P_{k} v, v\right)\right] \tag{3.10}
\end{equation*}
$$

Proof. If there exist $\tilde{v}^{H} \in I_{H} V_{H}, u_{k} \in E_{k} V_{h, k}, k=1,2, \cdots, M$, such that,

$$
\left\{\begin{array}{l}
v=\tilde{v}^{H}+\sum_{k=1}^{M} u_{k}  \tag{3.11}\\
a_{h}\left(\tilde{v}^{H}, \tilde{v}^{H}\right)+\sum_{k=1}^{M} a_{h}\left(u_{k}, u_{k}\right) \leq \beta a_{h}(v, v)
\end{array}\right.
$$

then (see [1])

$$
\begin{equation*}
a_{h}(v, v) \leq \beta a_{h}\left(P_{H} v+\sum_{k=1}^{M} P_{k} v, v\right) \tag{3.12}
\end{equation*}
$$

It is necessary to find a decomposition of $v$ which makes (3.11) true for some $\beta$. The subdomains $\left\{\Omega_{k}, k=1,2, \cdots, M\right\}$ are an open covering of $\Omega$. There exists a sufficiently smooth partition of unit for the open covering, $\left\{\varphi_{k}, k=1,2, \cdots, M\right\}$, such that

1. $\sum_{k=1}^{M} \varphi_{k}=1$, and $0 \leq \varphi_{k} \leq 1, k=1,2, \cdots, M$.
2. $\left|D \varphi_{k}\right| \leq C L^{-1},\left|D^{2} \varphi_{k}\right| \leq C L^{-2}, k=1,2, \cdots, M$.

Where $C$ is a constant independent of $M$ and the choice of subdomains.
For $v \in V_{h}$, define $\tilde{v}^{H}=I_{H} P Q_{h}^{1} v$, then $v$ can be written by

$$
v=\tilde{v}^{H}+\sum_{k=1}^{M} \varphi_{k}\left(v-\tilde{v}^{H}\right)
$$

The interpolation operator of Wilson element, for $T \in \mathrm{~T}_{h}$, is denoted by $\Pi_{T}$, and $\Pi_{h}$ is the interpolation operator corresponding to $\mathrm{T}_{h} . \Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)$ is well defined because $\varphi_{k}\left(v-\tilde{v}^{H}\right)$ is piecewise smooth. On the other hand, $\varphi_{k}$ is sufficiently smooth, and $v-\tilde{v}^{H}$
is continuous at the vertices. Hence $\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right) \in V_{h} . \Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right) \in E_{k} V_{h, k}$ since $\left.\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{\bar{\Omega}-\Omega_{k}}=0$. A decomposition of $v$ is obtained by

$$
\begin{equation*}
v=\tilde{v}^{H}+\sum_{k=1}^{M} \Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right) . \tag{3.13}
\end{equation*}
$$

Inequalities (2.1) and (2.9) and the interpolation property of $Q_{h}^{1}$ give

$$
\begin{equation*}
a_{h}\left(\tilde{v}^{H}, \tilde{v}^{H}\right) \leq C\left|\tilde{v}^{H}\right|_{1, h}^{2} \leq C|v|_{1, h}^{2} . \tag{3.14}
\end{equation*}
$$

Let $k \in\{1,2, \cdots, M\}, T \in \mathrm{~T}_{h}$ and $T \subset \bar{\Omega}_{k}$. Denote the center point of $T$ by $A_{T}^{0}$. By inequality (2.3), one has

$$
\begin{aligned}
\mid \Pi_{h}\left[\left(\varphi_{k}-\right.\right. & \left.\left.\Pi_{T}^{1} \varphi_{k}\right)\left(v-\tilde{v}^{H}\right)\right]\left.\right|_{0, T} ^{2} \leq C\left\{\sum_{1 \leq i, j \leq 4}\left|\varphi_{k}\left(v-\tilde{v}^{H}\right)\left(A_{T}^{i}\right)-\varphi_{k}\left(v-\tilde{v}^{H}\right)\left(A_{T}^{j}\right)\right|^{2}\right. \\
& \left.+h^{4}\left(\left|\frac{\partial^{2}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)}{\partial x^{2}}\left(A_{T}^{0}\right)\right|^{2}+\left|\frac{\partial^{2}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)}{\partial y^{2}}\left(A_{T}^{0}\right)\right|^{2}\right)\right\} \\
\leq & C\left\{\sum_{1 \leq i, j \leq 4}\left|\varphi_{k}\left(A_{T}^{i}\right)\left(\left(v-\tilde{v}^{H}\right)\left(A_{T}^{i}\right)-\left(v-\tilde{v}^{H}\right)\left(A_{T}^{j}\right)\right)\right|^{2}\right. \\
& \left.+\sum_{1 \leq i, j \leq 4} \mid\left(\varphi_{k}\left(A_{T}^{i}\right)-\varphi\left(A_{T}^{j}\right)\right)\left(v-\tilde{v}^{H}\right)\left(A_{T}^{j}\right)\right)\left.\right|^{2} \\
& +h^{4}\left(\left|\frac{\partial^{2} \varphi_{k}}{\partial x^{2}}\left(A_{T}^{0}\right)\right|^{2}+\left|\frac{\partial^{2} \varphi_{k}}{\partial y^{2}}\left(A_{T}^{0}\right)\right|^{2}\right)\left|\left(v-\tilde{v}^{H}\right)\left(A_{T}^{0}\right)\right|^{2} \\
& +h^{4}\left(\left|\frac{\partial \varphi_{k}}{\partial x}\left(A_{T}^{0}\right)\right|^{2}\left|\frac{\partial\left(v-\tilde{v}^{H}\right)}{\partial x}\left(A_{T}^{0}\right)\right|^{2}+\left|\frac{\partial \varphi_{k}}{\partial y}\left(A_{T}^{0}\right)\right|^{2}\left|\frac{\partial\left(v-\tilde{v}^{H}\right)}{\partial y}\left(A_{T}^{0}\right)\right|^{2}\right) \\
& \left.+h^{4}\left(\left|\frac{\partial^{2}\left(v-\tilde{v}^{H}\right)}{\partial x^{2}}\left(A_{T}^{0}\right)\right|^{2}+\left|\frac{\partial^{2}\left(v-\tilde{v}^{H}\right)}{\partial y^{2}}\left(A_{T}^{0}\right)\right|^{2}\right)\left|\varphi\left(A_{T}^{0}\right)\right|^{2}\right\}
\end{aligned}
$$

Denote Sobolev maximum semi-norm by $|\cdot|_{m, \infty, T}$. The property of $\varphi_{k}$ leads to

$$
\begin{align*}
\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, T}^{2} \leq & C\left\{\left(h^{2} L^{-2}+h^{4} L^{-4}\right)\left|v-\tilde{v}^{H}\right|_{0, \infty, T}^{2}\right. \\
& \left.+\left(h^{2}+h^{4} L^{-2}\right)\left|v-\tilde{v}^{H}\right|_{1, \infty, T}^{2}+h^{4}\left|v-\tilde{v}^{H}\right|_{2, \infty, T}^{2}\right\} . \tag{3.15}
\end{align*}
$$

From the inverse inequality, one gets

$$
\begin{align*}
\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, T}^{2} \leq & C\left\{\left(L^{-2}+h^{2} L^{-4}\right)\left|v-\tilde{v}^{H}\right|_{0, T}^{2}\right. \\
& \left.+\left(1+h^{2} L^{-2}\right)\left|v-\tilde{v}^{H}\right|_{1, T}^{2}\right\} . \tag{3.16}
\end{align*}
$$

Summing the above inequality for all $T \subset \bar{\Omega}_{k}$, one gets

$$
\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, h}^{2}=\sum_{T \in \mathbf{T}_{h}, T \subset \bar{\Omega}_{k}}\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, T}^{2}
$$

$$
\leq C \sum_{T \in \mathrm{~T}_{h}, T \subset \bar{\Omega}_{k}}\left\{\left(L^{-2}+h^{2} L^{-4}\right)\left|v-\tilde{v}^{H}\right|_{0, T}^{2}+\left(1+h^{2} L^{-2}\right)\left|v-\tilde{v}^{H}\right|_{1, T}^{2}\right\} .
$$

Summing the above inequality for all $k$, one has

$$
\sum_{k=1}^{M}\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, h}^{2} \leq C\left\{\left(L^{-2}+h^{2} L^{-4}\right)\left|v-\tilde{v}^{H}\right|_{0, h}^{2}+\left(1+h^{2} L^{-2}\right)\left|v-\tilde{v}^{H}\right|_{1, h}^{2}\right\} .
$$

where the fact, that the numbers of subdomains containing each elements in $\mathrm{T}_{h}$ are bounded, has been used.

Estimates (2.9) and (2.1) and the interpolation property of $Q_{h}^{1}$ give that

$$
\sum_{k=1}^{M}\left|\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right|_{1, h}^{2} \leq C\left(1+\frac{H^{2}}{L^{2}}\right)\left(1+\frac{h^{2}}{L^{2}}\right)|v|_{1, h}^{2}
$$

Since the norms $|\cdot|_{1, h}$ and $a_{h}(\cdot, \cdot)^{1 / 2}$ are equivalent, the above estimate and (3.14) lead to
$a_{h}\left(\tilde{v}^{H}, \tilde{v}^{H}\right)+\sum_{k=1}^{M} a_{h}\left(\Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right), \Pi_{h}\left(\varphi_{k}\left(v-\tilde{v}^{H}\right)\right)\right) \leq C\left(1+\frac{H^{2}}{L^{2}}\right)\left(1+\frac{h^{2}}{L^{2}}\right) a_{h}(v, v)$.
(3.10) follows.

The main theorem of the paper can be immediately obtained by (3.4), (3.5), (3.8) and (3.10).

Theorem. For Wilson element and the operator $I_{H}$ defined in section 2, there exists a constant $C$ independent of $H, h$ and the choice of subdomains, such that the condition number of $Q^{-1} A_{h}$ satisfies

$$
\begin{equation*}
\operatorname{Cond}\left(Q^{-1} A_{h}\right) \leq C\left(1+\frac{H^{2}}{L^{2}}\right)\left(1+\frac{h^{2}}{L^{2}}\right) \tag{3.18}
\end{equation*}
$$

Estimate (3.18) leads to that the condition number is independent of the scale of problem and the number of subdomains if $H=L$. So the optimal preconditioning is obtained.

## References

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[^0]:    * Received April 22, 1994.

