A CLASS OF THREE-LEVEL EXPLICIT DIFFERENCE SCHEMES*

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Abstract

A class of three-level six-point explicit schemes L_3 with two parameters s,p and accuracy $O(\tau h + h^2)$ for a dispersion equation $U_t = aU_{xxx}$ is established. The stability condition $|R| \le 1.35756176$ (s = 3/2, p = 1.184153684) for L_3 is better than |R| < 1.1851 in [1] and seems to be the best for schemes of the same type.

Any three-level explicit difference scheme for a dispersion equation $U_t = aU_{xxx}$ can be written in the form

$$U_{m+s}^{n+1} = \sum_{j=i}^{k} b_j U_{m+j}^n + \sum_{j} c_j U_{m+j}^{n-1}$$
 (*)

(*) is referred to as an "N-point" scheme, where N=k-i+1 (k>i). A class of six-point schemes L_3 containing two paremeters s and p is established in this paper. Their local truncation errors are $O(\tau h + h^2)$. The optimal stability condition obtained is $|R| \leq 1.35756176$ $(R = a\tau/h^3, \tau = \Delta t, h = \Delta x)$, which corresponds to s = 3/2, p = 1.184153684. This stability condition is an improvement on the result $|R| \leq 1.1851$ in [1] and seems to be the best condition for six-point schemes of the same type at present.

The schemes given in this note are as follows:

$$L_3: \quad U_{m+s}^{n-d+1} - U_{m+s}^{n-d} + U_{m-s}^{n+d} - U_{m-s}^{n+d-1} = 2R \sum_{j=0}^{2} C_j \left(U_{m-j+1/2}^n - U_{m-j-1/2}^n \right)$$
(1)

where a > 0 if d = 0, a < 0 if d = 1, s = 1/2, 3/2; $C_0 = 2.5p - 3$, $C_1 = -1.25p + 1$, $C_2 = 0.25p$.

For s = 1/2 and p = 1, the schemes L_3 become H_3 in [1].

Now we analyse the stability of schemes L_3 by the Fourier method. For definiteness, put $s=3/2,\,d=0$ (a>0). Let

$$U_m^n = \lambda^n e^{iqx_m}, \quad i^2 = -1, \ x_m = mh, \ q$$
-real number. (2)

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Substituting (2) into (1), we obtain the characteristic equation of schemes L_3 (see, [3]):

$$e^{iQ}\lambda^2 - 2F(Q)i\lambda - e^{-iQ} = 0, \quad Q = qh/2,$$
 (3)

$$F(Q) = 2R \sum_{j=0}^{2} C_{j} \sin(2j+1)Q + \sin(3Q)$$

$$=Rf(y,p)+g(y), \quad y=\sin Q, \quad 0\leq Q\leq \pi/2,$$

$$f(y,p) = 8y^3(py^2 - 1) = 8y^3(y - c)(y + c)/c^2, \quad p > 1, pc^2 = 1,$$
 (4)

$$q(y) = 3y - 4y^3, \quad 0 \le y \le 1.$$
 (5)

From equation (3) and [2,4], it follows that the stability condition of L_3 is |Rf(y,p)+g(y)|<1 or

$$|R| < \sup_{p} \inf_{0 < y \le 1} G(y, p), \tag{6}$$

$$G(y,p) = \begin{cases} -(1+g(y))/f(y,p), & 0 < y < c, \\ (1-g(y))/f(y,p), & 0 < y \le 1. \end{cases}$$
 (7)

In order to find $\inf G(y,p)$ in the interval $0 < y \le 1$ for any fixed p > 1, the properities of G(y,p) are discussed in the following.

1. In the case 0 < y < c, we have

$$\partial G/\partial y = 8y^{2}(2y+1)W(y,p)/f(y,p)^{2},$$

$$W(y,p) = py^{2}(-4y^{2}+2y+5)-3,$$

$$W(0,p) = -3, \quad W(c,p) = 2(2c+1)(1-c) > 0,$$

$$\partial W/\partial y = py(16y+10)(1-y) > 0,$$

$$\partial G/\partial p = 8y^{5}(1+g(y))/f(y,p)^{2} > 0.$$
(8)

From the above equalities, we see that there exists a unique zero point z of W(y,p) or $\partial G/\partial y$, and z is also a unique minimum point of G(y,p) for 0 < y < c because G(0,p), $G(c,p) \to \infty$, and G(y,p) is obviously a monotonically increasing function of p for any $y \in (0,c)$ (see, (9)). Thus, for arbitrary numbers p_1 , p_2 , c_1 , c_2 satisfying $p_1 > p_2$ and $p_1c_1^2 = p_2c_2^2 = 1$, we have $c_1 < c_2$, and

$$\inf_{0 < y < c_1} G(y, p_1) = G(z_1, p_1) > G(z_1, p_2) \ge \inf_{0 < y < c_2} G(y, p_2) = G(z_2, p_2). \tag{10}$$

This verifies that $\inf G(y,p)$ (0 < y < c) is a monotonically increasing function of p > 1.

2. In the case of $c < y \le 1$, we have

$$\partial G/\partial y = 8y^{2}H(y,p)/f(y,p)^{2},$$

$$H(y,p) = pL(y) - 6y + 3, \quad 1
$$L(y) = -8y^{5} + 12y^{3} - 5y^{2} = 4y^{2}(2y - 1)(y_{1} - y)(y - y_{2}),$$

$$y_{1} = (\sqrt{21} - 1)/4, \quad y_{2} = -(\sqrt{21} + 1)/4,$$
(11)$$

$$p_0 = p(z) = \min_{0.5 < y < y_1} (6y - 3)/L(y) = 3.510857143, \quad z = 5/8,$$

$$c_0 = c(z) = 0.533695352 > 1/2, \quad pc^2 = 1,$$

$$\partial G/\partial p = -8y^5(1-g(y))/f(y,p)^2 < 0,$$
 (12)

$$\lim G(y,p) = 0, \quad y \to 1/2 \text{ for any } p > 1.$$
 (13)

From (11)-(13), with no loss of generality, we may assume that $c \geq c_0$ or $p \leq p_0$. Under this assumption, there are H(y,p) < 0, $\partial G/\partial y < 0$ and so G(y,p) is a monotonically decreasing function of y for $c < y \leq 1$, Consequently,

$$\inf_{0 < y \le 1} G(y, p) = G(1, p) = 1/(4p - 4), \quad 1 < p \le p_0. \tag{14}$$

From the above discussion, we see that if we choose a parameter p such that

$$G(1,p) = \inf_{0 \le y \le c} G(y,p) = G(z,p), \tag{15}$$

then stability condition (6) will be the best.

In order to calculate the minimum point z, solve for p from the equation W(y,p)=0 (see (8)):

$$p = 3/(5y^2 + 2y^3 - 4y^4), \quad y = z. \tag{16}$$

Substituting (16) into (15), we obtain

$$(y+1)^{2}(y-1)(2y+1)A(y) = 0,$$

$$A(y) = 4y^{3} - 8y^{2} + 3 = 0, \quad 0 < y < c.$$
(17)

From A(-1) = -9, A(0) = 3, A(1) = -1 and A(2) = 3, it follows that there exists a unique zero point z of A(y) in the interval (0,1). The following numerical results are calculated by the formulas (17), (16), (14), (4), (5) and (6).

$$z = 0.7859966342,$$
 $A(z) = 2E - 10,$ $p^* = p(z) = 1.184153684,$ $c^* = c(z) = 0.918958638,$ $pc^2 = 1,$ (18) $G(1,p) = 1.357561766,$ $G(z,p) = 1.357561765,$ $|R| \le 1.35756176.$ (19)

Up to now, we obtained the stability condition (18)-(19) of L_3 with s = 3/2, d = 0. Using the same method, it is easy to prove that (18)-(19) is also the stability condition of L_3 with s = 3/2, d = 1.

By repeating the above procedure, we can show that the best stability condition of L_3 in the case of s = 1/2 is p = 1, $|R| \le 1.1851$, that is the result of [1].

Example. Use a difference method to solve the initial-boundary value problem for the equation $U_t = aU_{xxx}$ (a = 1, -1); its solution is

$$U(x,t) = \cos(x-at), \quad 0 \le x \le 1, \quad t > 0.$$
 (20)

The numerical computation was carried out on a pocket computer PC-1500. At the mesh point, U_m^n denotes the approximate solution computed by difference scheme L_3

 $(s=3/2,h=0.01,p=p^*,M=1/h)$, in the order of $m=0,1,2,\ldots,M$ for a>0 and $m=M,M-1,\ldots,1,0$ for a<0. The necessary boundary values and initial values in computation were calculated by (20). Some data of errors $U_m^n-U(X_m,T_n)$ are listed in Tables 1-4. From the tables, we see that the data in Tables 1-2 are of numerical stability and in Tables 3-4 are of numerical unstability. These results all coincide with the stability condition (18)-(19).

Table 1. a = 1, R = 1.357561

2.5				
m n	2	202	402	602
31	4.3E - 11	4.80E - 09	1.09E - 08	-1.73E - 08
E 1	05F 11	7.83E - 09	1.71E - 08	2.71E - 08
71	1.94E - 10	1.18E - 08	2.35E - 08	3.78E - 08
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Table 2. a = -1, R = -1.357561

m n	2	202	402	602	
25	1.9E - 11	-4.66E-09	-6.92E - 09	-1.82E-08	
50	$-0.4E \stackrel{4}{\sim} 11$	-1.03E - 08	-1.72E-08	-2.07E-08	
75	-1.42E - 10	-1.63E - 08	-3.40E - 08	-4.97E-08	
10	1.000	7-10 A 140 A			

Table 3. a = 1, R = 1.36

m n	2	202	402	602
31	5.5E - 11	-4.53E-07	-5.60E - 03	-67.79
51	1.11E - 10	-1.08E - 06	-9.98E-03	-125.38
71	2.25E - 10	-9.47E - 07	-1.18E-02	-150.12

Table 4. a = -1, R = -1.36

				49
m n	2	202	402	602
25	2E-11	-5.35E-07	-5.81E - 03	-75.49
50	-6E - 11	6.52E - 07	5.17E - 03	63.89
75	-2.23E-10	-8.89E - 68	-2.11E-03	-24.96

References

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