# EXACT SOLUTIONS OF (2+1)-DIMENSIONAL NONLINEAR SCHRÖDINGER EQUATION BASED ON MODIFIED EXTENDED TANH METHOD * 

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#### Abstract

In this paper, the modified extended tanh method is used to construct more general exact solutions of a ( $2+1$ )-dimensional nonlinear Schrödinger equation. With the aid of Maple and Matlab software, we obtain exact explicit kink wave solutions, peakon wave solutions, periodic wave solutions and their 3D images.

Keywords nonlinear Schrödinger equation; modified extended tanh method; kink wave solution; peakon wave solution; periodic wave solution


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## 1 Introduction

It is well known that Schrödinger equation is one of the most basic equation of quantum mechanics. It reflects the state of micro particle changing with time. As it is a powerful tool for solving non relativistic problems in atomic physics, it has been widely used in the field of atomic, molecular, solid state physics, nuclear physics, chemistry and so on. Recently, searching and constructing exact solutions of nonlinear partial differential (NLPD) equation is very meaningful for it can describe the problems of mechanics, control process, ecological and economic system, chemical recycling system and epidemiological.

In the past several decades, much efforts have been made on this aspect and many useful methods have been proposed such as inverse scattering method, Jacobi elliptic function method, F-expansion method, Darboux transform, the sine-cosine method and the tanh method and so on [1-18]. Among them, the tanh method is

[^0]widely used as it can find exact as well as approximate solutions in a systematic way. Subsequently, Fan has proposed an extended tanh method and obtained the travelling wave solutions that can not be obtained by the tanh method. Based on this approach, we employ the modified extended tanh method to construct a series of exact travelling wave solutions of a ( $2+1$ )-dimensional nonlinear Schrödinger (NLS) equation as
\[

$$
\begin{equation*}
i u_{t}+\alpha u_{x x}+\beta u_{y y}+r\left|u^{2}\right| u=0 . \tag{1}
\end{equation*}
$$

\]

The rest of this paper is organized as follows. In Section 2, we shall introduce the modified extended tanh method. In Section 3, we illustrate this method in detail with the ( $2+1$ )-dimensional nonlinear Schrödinger (NLS) equation. In Section 4, the image simulations of exact Travelling Wave Solutions of (1) are given. Finally, a short conclusion is given in Section 4.

## 2 The Modified Extended Tanh Method

In this section, we review the modified extended tanh method.
The modified extended tanh method is developed by Malflied in [10,11], and used in [12-14] among many others. Since all derivatives of a tanh can represented by tanh itself, we consider the general NLPDE in two variables

$$
H\left(u, u_{t}, u_{x}, u_{x} x, u_{t} t, u_{x} t, \cdots\right)=0 .
$$

Now we consider its travelling $u(x, t)=u(\xi)$, where $\xi=x-c t$ or $\xi=x+c t$ and the equation becomes an ordinary differential equation. We apply the following series expansion

$$
u(\xi)=\sum_{i=0}^{N} a_{i} \phi^{i}+\sum_{i=1}^{N} b_{i} \phi^{-i}, \quad \phi^{\prime}=b+\phi^{2},
$$

where $b$ is a parameter to be determined, $\phi=\phi(\xi)$ and $\phi^{\prime}=\frac{\mathrm{d} \phi}{\mathrm{d} \xi}$.
To determine the parameter $N$, we usually balance the linear terms of highestorder in the resulting equation with the highest-order nonlinear terms. Then we can get all coefficients of different powers of $\phi$ and determine $a_{i}, b_{i}, b, c$ by making them equal to zeros.

The Riccati equation has the following general solutions:
(a) If $b<0, \phi=-\sqrt{-b} \tanh (\sqrt{-b} \xi)$;
(b) if $b>0, \phi=\sqrt{b} \tan (\sqrt{b} \xi)$;
(c) if $b=0, \phi=-1 / \xi$.

## 3 Exact Travelling Wave Solutions of (1)

We consider the travelling wave solution $u(x, y, t)=u(\xi), \xi=x+k y-c t$ of (1), and also

$$
\begin{equation*}
u(\xi)=P(\xi)+i Q(\xi) . \tag{2}
\end{equation*}
$$


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