
ON SOME FORWARD-BACKWARD DIFFUSION EQUATIONS

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Dedicated to Professor K. C. Chang on his seventieth birthday

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Abstract We describe an application of the partial differential inclusion method to the existence of Lipschitz weak solutions for certain forward-backward diffusion equations including the one-dimensional version of the Perona-Malik equation in image processing.

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In some earlier works of Professor Chang, elliptic equations with discontinuous nonlinearities were studied and set-valued mappings are used to solve such equations (see, for example [1-7] In this talk we use the partial differential inclusion method for set-valued mappings to study mainly the existence problem of the following one-dimensional forward-backward diffusion equation under the homogeneous natural boundary condition:

$$\begin{cases} u_t = a(u_x)_x, & (t, x) \in (0, T) \times (0, 1) := Q_T, \\ u(0, x) = u_0(x), & 0 \leq x \leq l, \\ a(u_x(t, 0)) = a(u_x(t, l)) = 0, & 0 \leq t \leq T, \end{cases} \quad (1)$$

where the flux function $a(s)$ is not monotone. There are many examples of such non-monotone $a(\cdot)$ arising from applied mathematics such as

Model 1) the general coercive forward-backward diffusion model [8] where $a(s)s > c|s|^2$ while $a(\cdot)$ is not monotone,

Model 2) the well-known one-dimensional Perona-Malik model where $a(s) = s/(1+s^2)$ in image processing for edge detection [9-13],

Model 3) the simplest double well model in the study of microstructure $a(s) = f'(s)$ with $f(s) = \text{dist}^2(s, \{-1, 1\})$ the squared distance function and its generalizations under lower order perturbations [14, 15].

There are some other related models such as

Model 4) the fast diffusion model where $a(s) = \text{sign}(s) \log |s|$ [16]. We may consider the Cauchy problem or the initial boundary value problem under the Dirichlet condition.

$$\begin{cases} u_t = a(u_x)_x, & (t, x) \in (0, T) \times \mathbf{R}, \\ u(0, x) = u_0(x), & x \in \mathbf{R} \end{cases} \quad (2)$$

Model 5) the two-dimensional model based on the Perona-Malik numerical scheme [9, 12]:

$$\begin{cases} u_t = a(u_x)_x + a(u_y)_y, & (t, x, y) \in (0, T) \times D := Q_T, \\ u(0, x, y) = u_0(x, y), & (x, y) \in \bar{D}, \\ \mathbf{a}(\nabla u) \cdot n = 0, & \text{on } \partial D, \quad 0 \leq t \leq T, \end{cases} \quad (3)$$

where D is the unit square in \mathbf{R}^2 , $\mathbf{a}(\nabla u) = (a(u_x), a(u_y))$ with $a(s) = s/(1 + s^2)$ and n is the outward normal vector on ∂D .

We mainly describe the method for solving Problem 1 and Problem 2 above and briefly explain how we deal with other models.

In the pioneering work of Klaus Höllig [8], infinitely many weak solutions were constructed under the main constitutive assumption that function $a : \mathbf{R} \rightarrow \mathbf{R}$ in (1) is piecewise affine, as illustrated in Figure 1 below. The construction of solutions in [8] depends heavily on this constitutive requirement.

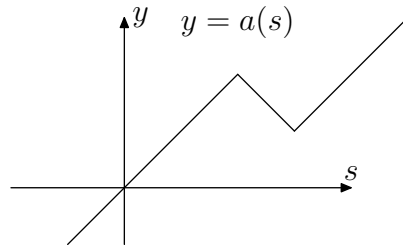


Figure 1: Shape of $y = a(s)$ considered by Höllig

However, it is difficult to generalize Höllig's method to solve (1) with $a(\cdot)$ given by Figure 2 below.

In order to solve (1), we have to look for methods alternative to that of Höllig's.

Problem 1 A generalization of Höllig's model

Hypothesis (A) (illustrated in Fig.2). The function $a : \mathbf{R} \rightarrow \mathbf{R}$ satisfies

- i) there are two numbers $0 < s_1 < s_2$, such that $a \in C^{2,1}([s_1, s_2]^c) \cap C^0((s_1, s_2)^c)$;
- ii) for $s \in [s_1, s_2]^c$, $a'(s) > 0$, $0 < a(s_2) < a(s_1)$;